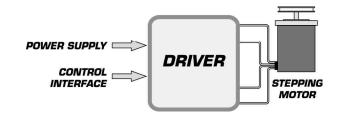


# **IM483**

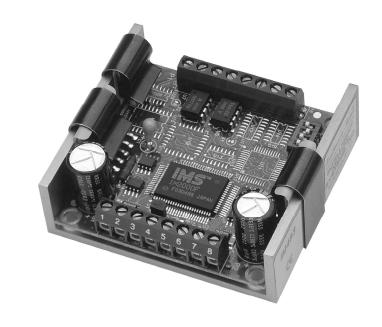
## HIGH PERFORMANCE MICROSTEPPING DRIVER

#### **FEATURES**

- Low Cost
- Extremely Small (2.7 x 3.0 x 1.2 in.) (70 x 69 x 31 mm)
- High Input Voltage (48V)
- High Output Current (3 Amps RMS, 4 Amps Peak)
- Advanced Surface Mount and ASIC Technology
- No Minimum Inductance
- Single Supply
- Up to 10 MHz Step Clock Rate
- Opto-Isolated Inputs
- Fault Output
- Short Circuit and Over Temperature Protection
- Up to 51,200 Steps/Rev
- Microstep Resolutions Can Be Changed On-The-Fly without Loss of Motor Position
- 20 kHz Chopping Rate
- Automatically Switches Between Slow and Fast Decay for Unmatched Performance
- 14 Selectable Resolutions Both in Decimal and Binary
- Adjustable Automatic Current Reduction
- At Full Step Output
- Optional On-board Indexer and Encoder Feedback



**BLOCK DIAGRAM** 



#### **DESCRIPTION**

The IM483 is a high performance, low cost microstepping driver that incorporates advanced surface mount and ASIC technology. The IM483 is small, easy to interface and use, yet powerful enough to handle the most demanding applications.

The IM483 has 14 different resolutions (both in binary and decimal) built into the driver. These resolutions can be changed at any time. There is no need to reset the driver.

This feature allows the user to rapidly move long distances, yet precisely position the motor at the end of travel without the expense of high performance controllers.

The development of proprietary circuits has minimized ripple current while maintaining a 20 kHz chopping rate. This prevents additional motor heating that is common with drivers requiring higher chopping rates. Now low inductance stepper motors can be used to improve high speed

performance and system efficiency. The IM483 also comes with an optional on-board indexer to provide design engineers with versatility and power unmatched in today's industry.

The IM483 is priced lower to provide customers with affordable state-of-the-art technology for that competitive edge needed in today's market.

## SPECIFICATIONS



#### **ELECTRICAL**

Input Voltage Drive Current (Per Phase) 0.4 to 3 Amps RMS, 4 Amps Peak Isolated Inputs Step Frequency (Max)

Protection

\*Recommended Power Supply: ISP200-4

IM483

+12 to 48 Volts\* (Includes Motor Back EMF)

\_\_\_\_\_ Step Clock, Direction, Enable & Reset

10 MHz

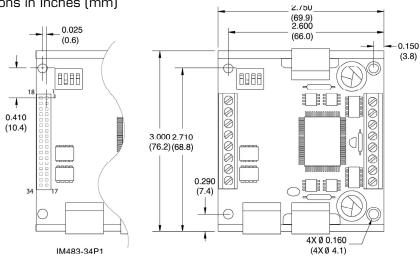
Steps per Revolution (1.8° Motor) 400, 800, 1000, 1600, 2000, 3200, 5000, 6400, 10000, 12800, 25000, 25600,

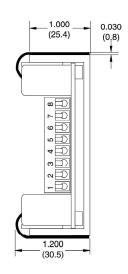
50000, 51200

Thermal and All Way Short Circuit

#### MECHANICAL

Dimensions in Inches (mm)





#### **TEMPERATURE**

Case\* (Max) O to +70° C

#### **OPTIONS**

H-4X Heat Sink

TN-48 \_\_\_\_Thermal Pad

21. Step Clock Out

23. Resolution Select O

24. Resolution Select 2

22. Direction Out

-8P2 \_\_\_\_\_8 Position 0.045" sq Pin P2 Connector

with 8 Position 0.025" sq Pin P1 Connector

-34P1 \_\_\_\_\_ 34 Position 0.025" sq Pin P1 Connector

Plug Type Terminal Strip for P1 and P2 -PLG \_\_\_\_\_

Connectors

PLG-R(1/2) \_\_Mating Connectors for the -PLG Option

U3-CLP \_\_\_\_Side Mounting Clip Set

#### PIN FUNCTIONS

#### Connector P1 (8 Pin)

- 1. No Connection
- 2. Step Clock
- 3. Direction
- 4. Opto Supply
- 5. Enable
- 6. Reset
- 7. Fault.
- 8. On Full Step

### Connector P1\* (34 Pin)

- 3. Resolution Select 3 16, 26.0n Full Step
- 4. Step Clock In
- 6. Direction In
- 8. Opto Supply

- 10. Enable
- 12. Reset
- 14. Fault.
- 25. Resolution Select 1
- 27. Ground
- \*Pins not shown are no connections.

#### Connector P2

- 8. Phase A
- 7. Phase A
- 6. Phase B
- 5. Phase B
- 4. V+ (12V to 48V)
- 3. Ground
- 2. Current Adjust
- 1. Reduction Adjust

<sup>\*</sup>External heat sink may be required to maintain case temperature.