



SKR

LM Guide Actuators Featuring Caged Ball Technology

Caged Ball Technology Offers

Long life and long-term, maintenance-free operation Excellent high speed performance Reduced variations in rolling resistance and low noise





Type SKR LM Guide Actuator with Caged Ball Technology

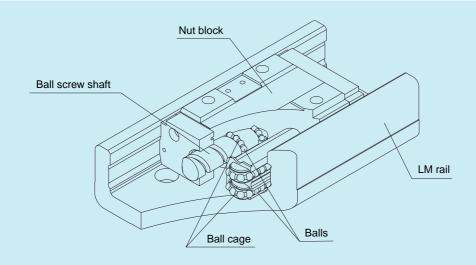


Figure 1 Construction of SKR-type LM Guide Actuator with Caged Ball Technology

Construction and Features

The SKR-type LM guide actuator with Caged Ball Technology is a compact actuator that places a nut block(s) that integrates an LM block and ball screw nut onto the inside of the LM rail of a U-shaped cross-sectional form. Moreover, the addition of the LM guide and ball screw sections with Caged Ball Technology allows the SKR-type LM guide actuator to achieve higher speed, lower noise, longer maintenance-free operation, and other features in comparison with the conventional KR-type.

1. Four-way Equal Load Rating

Each row of balls is arranged at a contact angle of 45° so that loads acting on the nut block in the four directions (radial, reverse-radial, and two lateral directions) show the same load rating. Thus, the SKR-type LM guide actuators can be used in any position.

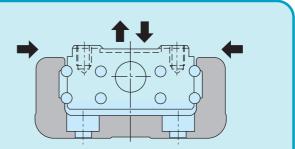


Figure 2 Load-carrying Capacity and Contact Angles of the SKR

2. High Rigidity

The adoption of the LM rail of a U-shaped cross-sectional form allows improved rigidity against moment

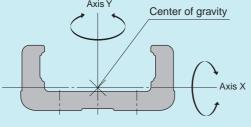


Figure 3 Sectional View of LM Rail

Table 1 LM Rail Cross-sectional Characteristics

I Init mm⁴

			Unit.mm
Model No.	lx	ly	Mass (kg/100mm)
SKR33	5.35 ×10⁴	3.52 ×10⁵	0.61
SKR46	2.05 ×10⁵	1.45 ×10 ⁶	1.26

Ix = geometrical moment of inertia around axis X

I_Y = geometrical moment of inertia around axis Y

1

3. High Accuracy

The linear motion guide raceway has four rows of circular arc grooves that provide smooth motion by mere pre-load; clearance-free, highly rigid guidance is obtained. In addition, changes in frictional resistance resulting from load variations are minimized, allowing the SKR-type to achieve high-precision feed.

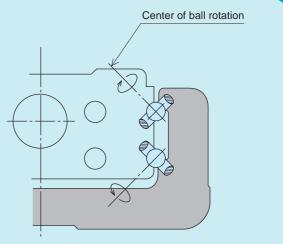


Figure 4 Contact Structure of SKR-Type

SKR33

10mm

4. Space Saving The integration of a LM guide raceway on both side faces of a nut block and the integration of a ball screw nut at the center of the nut block allow the SKR-type to achieve high rigidity and high precision in a minimal space. 10mm SKR46

5. Long Life Span and Long-term Maintenance-free Operation

Thanks to the effectiveness of its ball retainers, the SKR has improved grease retention capability. allowing it to achieve a long life span and long-term maintenance-free operation.

The SKR achieves a longer life span because its basic dynamic load rating at the LM guide and ball screw sections is greater than that of the conventional KR models (in the case of the KR3310, three times greater). The rated life span can be calculated by the following equation.

LM guide

 $L = (C / P)^{3} \times 50$

- L : rated life span (km)
- C : Basic dynamic load rating (N)
- P : carrying load (N)

Ball screw

 $L = (Ca / Fa)^3 \times 10^6$

L : rated life span (rev.)

Ca : Basic dynamic load rating (N)

Fa : carrying load in axial direction (N)

From the noted equations, the greater the Basic dynamic load rating, the longer the life span for both the LM guide and ball screw sections.

Table 2 Comparison of the Basic Dynamic Load Rating between the SKR and Conventional KR Types

Basic dynamic load rating		SKR3310	KR3310	SKR4620	KR4620
LM Guide unit	Long type block	17000	11600	39500	27400
	Short type block	11300	4900	28400	14000
Ball screw unit		2700	1760	4240	3040



6. High Speed

Through the use of Caged Ball Technology, the SKR-type is compatible with the latest high-speed rotational AC servo-motors (6000 min⁻¹), achieving higher speeds than the conventional KR-type. The ball screw lead settings of the conventional KR33 type were 6 mm and 10 mm. To achieve a higher feed rate, a 20 mm ball screw lead has been added to the new SKR 33 series.

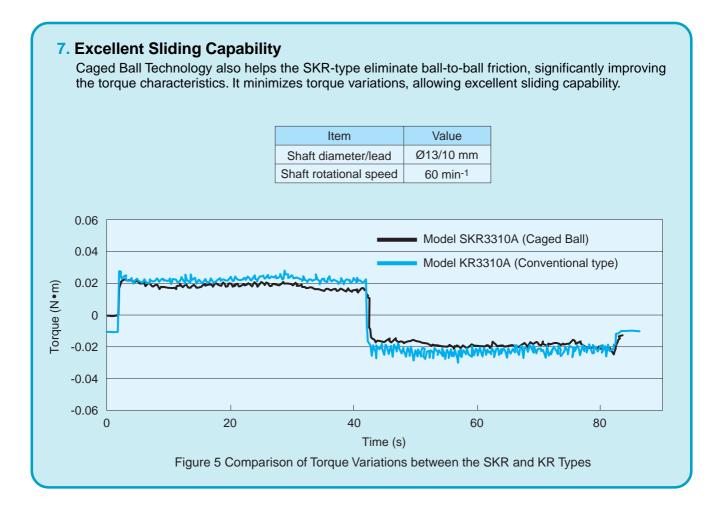
	Ball Screw	LM rail length	Maximum trave		
Model No.	lead (mm)	(mm)	Long block Short bloc		
		150	600		
		200	600		
		300	600		
	06	400	6	600	
		500	6	600	
		600	552	530	
		700	393	364	
		150	1,0	000	
		200	1,0	000	
		300	1,0	000	
SKR33	10	400	1,0	000	
		500	1,0	000	
		600	920	839	
		700	656	607	
	20	150	2,000	—	
		200	2,000	—	
		300	2,000	—	
		400	2,000	—	
		500	2,000	—	
		600	1,780	—	
		700	1,276	—	
		340	1,0	— 000	
		440	1,000		
	10	540	1,0	000	
	10	640	1,000	914	
		740	736	667	
SKR46		940	431	400	
SIXIX40		340	2,0	000	
		440	2,0	000	
	20	540	2,0	000	
	20	640	1,988	1,774	
		740	1,433	1,300	
		940	845	784	

Table 3 Maximum Traverse Rate

The maximum travel speed of the SKR-type is limited by the critical speed of the ball screw shaft, regardless of the maximum rotational speed (6000 min⁻¹) of the motor. Please keep this in mind when using the SKR-type in high-speed applications.

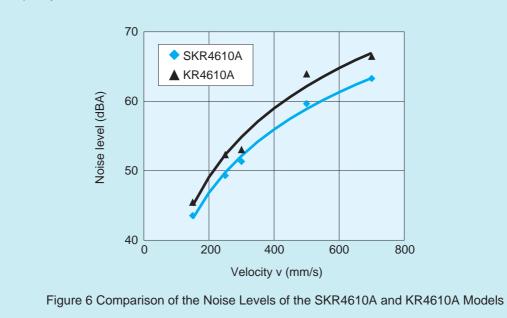
Please contact THK if you are considering using an SKR model at a rate higher than the maximum travel speed noted above.

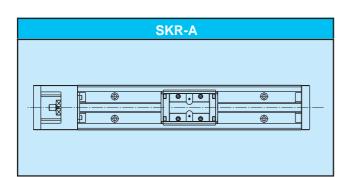




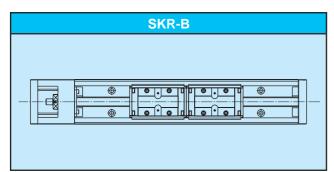
8. Low Noise

The use of Caged Ball Technology in the LM guide and ball screw allows the SKR-type to eliminate the noise caused by the balls colliding. This lets the SKR-type achieve low noise emission and a pleasing sound quality.



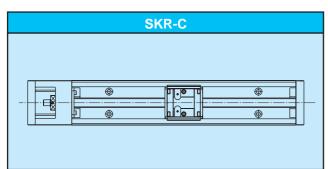


Models

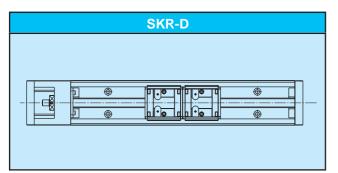


This is the typical SKR model.

This is the model in which two nut blocks of the SKR-A model are provided to achieve higher rigidity, higher load capacity, and higher precision.



This is the model in which the full length of the SKR-A model nut block is shortened to have a longer stroke. Note that the SKR3320 model has no short type block.



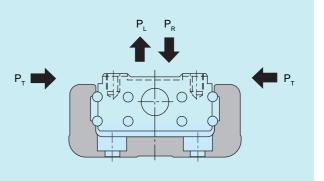
This is the model in which two SKR-C model nut blocks are provided. By placing two blocks, it achieves high rigidity within the application limits.

Note that the SKR3320 model has no short type block.

Load Rating and Static Permissible Moment in Each Direction

Load Rating

The SKR-type LM guide actuators with Caged Ball Technology consist of the LM guide, ball screw, and support bearing. Table 4 shows the load rating.



• LM guide section unit

The SKR-type can carry loads in all directions, i.e., the radial, reverse-radial, and two lateral directions. The basic load rating is the same in these four directions and their values are shown in Table 4.

• Ball screw section unit

The SKR-type can carry loads in the axial direction since it incorporates a ball screw nut in the nut block. The basic load rating value is shown in Table 4.

• Support bearing unit

The SKR-type can carry loads in the axial direction since it incorporates an angular bearing in housing A. The basic load rating value is shown in Table 4.

Equivalent Load (LM Guide Unit)

When loads are simultaneously applied to the SKR-type's LM guide in all directions, the equivalent load is obtained by the following equation.

$$\mathsf{P}_{\mathsf{E}} = \mathsf{P}_{\mathsf{R}} \left(\mathsf{P}_{\mathsf{L}} \right) + \mathsf{P}_{\mathsf{T}}$$

P _F : equivalent load	(N)
In the radial direction	
In the reverse-radial direction	
In the lateral directions	
P _R : radial load	(N)
P : reverse-radial load	(N)

 P_{τ}^{L} : load in the lateral directions (N)

Model		SKR33		SKR46			
Basic dynamic		Long nut block types A, B 1		17000		39500	
	load rating C (N)	Short nut block types C, D	11300			28400	
LM Guide	Basic static	Long nut block types A, B		20400		459	00
LIVI Guide	load rating C_{\circ} (N)	Short nut block types C, D		11500		287	00
		Normal grade, high accuracy grade	C) to -0.004	1	0 to –	0.006
Radial clearance (mm)		Precision quality grade	-0.004 to -0.012		012	-0.006 to -0.016	
	Screw shaft outer diameter (mm)		13		15		
	Lea	ad (mm)	6	10	20	10	20
Ball Screw	Thread mind	or diameter (mm)	10.8		12.5		
Dall Sciew	Ball center-to-c	enter diameter (mm)	13.5		15.75		
	Basic dynami	c load rating C _a (N)	4400	2700	2620	4350	4240
	Basic static load rating C _{0a} (N)		6290	3780	3770	6990	7040
Support	Basic dynamic load rating C _a (N)		6250			6700	
Bearing				2700		33	30

Table 4 Load rating

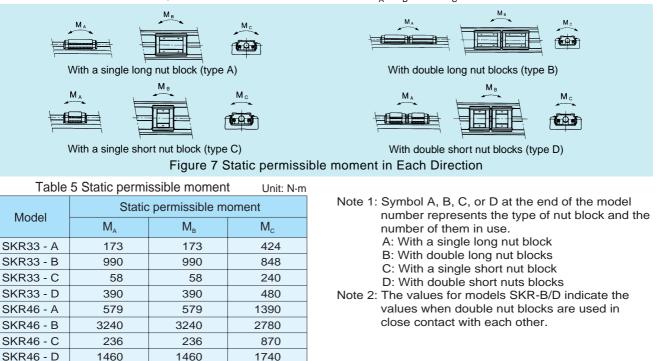
Notes: • The load rating of the LM guide is the load rating per nut block.

• Model SKR3320 has no short type block.



Permissible Moment (LM Guide Unit)

The SKR-type's LM guide section can carry moment loads in all directions, even though it uses only one nut block. Table 5 shows static permissible moment values in the M_{A} , M_{B} , and M_{C} directions.



Service Life

The SKR-type LM guide actuator with Caged Ball Technology consists of the LM guide, ball screw, and support bearing. The Service Life of each constituting component can be calculated based on the basic dynamic load rating shown in Rated Loads (Table 4 on p. 6).

Calculation of Service Life

1) LM Guide Unit

Nominal Life

The nominal life (L) refers to the total traveling distance that 90% of a group of the same LM guides can achieve without flaking (flakes peeling off the metal surface) when these LM guides are individually moved under the same conditions. The nominal life of the LM guide can be obtained by equation (1).

$$L = \left(\frac{f_c \cdot C}{f_w \cdot P_c}\right)^3 \times 50$$
(1)
$$L : Nominal life (km)$$

$$C : Basic dynamic load rating (N)$$

(N) : Calculated applied load ۰C

- fw : Load factor (see Table 7)
- fc : Contact factor (see Table 6)
- If moment is acted on the SKR-type when using the SKR-A/-C type or the SKR-B/-D type of closely linked double nut blocks. multiply the acting moment by the equivalent coefficient shown in Table 8 to calculate equivalent load.

 $P_m = K \cdot M$

- Pm : Equivalent load (per nut block) (N) Κ
 - : Equivalent moment factor
- : Applied moment (N·mm) Μ

(If the SKR-type is used using three or more nut blocks or with the span separated, contact THK.)

Particularly, if moment acts upon the SKR-B or SKR-D, use the following equation:

$$\mathsf{P}_{\mathsf{m}} = \frac{\mathsf{K}_{\mathsf{c}} \cdot \mathsf{M}_{\mathsf{c}}}{2}$$

- If a radial load (P) and moment load act on the SKR-type simultaneously, use the following equation to calculate the life span: $P_E = P_m + P$
 - PE : Overall equivalent radial load (N)



Service Life Time

When the nominal life (L) is obtained, the life span can be calculated by equation (2) if the stroke length and reciprocations of the system per minute are defined.

$L = - \frac{L \times 10^6}{10^6}$	(2)
$L_h = \frac{1}{2 \cdot \ell_s \cdot n_1 \times 60}$	(2)
L _h : Service life time	(h)
ℓ_s : Stroke length	(mm)
	(

n₁: Number of reciprocations per minute (min⁻¹)

2) Ball Screw Unit and Bearing Unit (Fixed side)

Nominal Life

The nominal life (L) refers to the total number of revolutions that 90% of a group of the same Ball Screw (Bearings) can achieve without flaking when individually operated under the exact conditions. The nominal life of the Ball Screw Unit or bearing unit (fixed side) is calculated by equation (3).

$$L = \left(\frac{C_{a}}{f_{W} \cdot F_{a}}\right)^{3} \times 10^{6}$$
(3)

$$L : \text{Nominal life} \qquad (rev.)$$

$$C_{a} : \text{Basic dynamic load rating} \qquad (N)$$

$$F_{a} : \text{Axial load} \qquad (N)$$

f_w : Load factor (see Table 7)

Service Life Time

When the nominal life (L) is obtained, the life span can be calculated by equation (4) if the stroke length and reciprocations of the system per minute are defined.

(4)	
-(4)	
	(h)
	(mm)
	(min ⁻¹)
	(mm)
	-(4)

f_c: Contact Factor

If two nut blocks are used and closely linked together in the SKR-B or SKR-D type, multiply the basic load rating by the contact factor shown in Table 6.

Table 6 Contact Factor (fc)

Block type	Contact Factor fc
A/C Type	1.0
B/D Type	0.81

f_w: Load Factor

Table 7 shows the load factor.

Table 7	Load	Factor	(f_w)
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Vibration or Impact	Speed (V)	f _w
Faint	Very low: $V \leq 0.25 \text{ m/s}$	1.0 to 1.2
Weak	Slow:0.25 < V \leq 1.0 m/s	1.2 to 1.5
Medium	Medium:1.0 < V \leq 2.0 m/s	1.5 to 2.0
Strong	High:V > 2.0 m/s	2.0 to 3.5

K: Moment Equivalent Factor (LM guide Unit)

If a moment load is incurred, the load-carrying distribution on the LM guide increases locally. In this case, multiply the moment value with the moment equivalent factor shown in Table 8 to make the load calculation.

 K_A , K_B , and K_C show the moment equivalent loads in the M_A , M_B , and M_C directions respectively.

Model No.	K _A	K _B	K _c
SKR33 - A	1.42×10 ⁻¹	1.42×10 ⁻¹	5.05×10 ⁻²
SKR33 - B	2.47×10 ⁻²	2.47×10 ⁻²	5.05×10 ⁻²
SKR33 - C	2.39×10 ⁻¹	2.39×10 ⁻¹	5.05×10 ⁻²
SKR33 - D	3.54×10 ⁻²	3.54×10 ⁻²	5.05×10 ⁻²
SKR46 - A	9.51×10 ⁻²	9.51×10 ⁻²	3.46×10 ⁻²
SKR46 - B	1.70×10 ⁻²	1.70×10 ⁻²	3.46×10 ⁻²
SKR46 - C	1.46×10 ⁻¹	1.46×10 ⁻¹	3.46×10 ⁻²
SKR46 - D	2.36×10 ⁻²	2.36×10 ⁻²	3.46×10 ⁻²

Table 8 Moment Equivalent Factor (K)

 K_A : moment equivalent factor in the M_A direction K_C : moment equivalent factor in the M_C direction

 K_B : moment equivalent factor in the M_B direction

Note: For the SKR-B and SKR-D types, the moment equivalent factor shows the value applied when two nut blocks are closely linked together.



Accuracy Standards

The tables below show the accuracy standards of the SKR-type.

Table 9-1 Normal Grade (No Symbol)

Table 9 Accuracy Standards

Table 9-1 Normal Grade (No Symbol) Unit: m						
Model No.	Rail Length	Positioning Repeatability	Positioning Accuracy	Running of Parallelism	Backlash	Starting Torque (N-cm)
	150					
	200					7
	300		No standard defined	No standard defined	0.020	
SKR33	400	± 0.010				
	500					
	600					
	700					
	340					
	440				0.020	
	540		No standard	No standard		
SKR46	640	± 0.010	defined	defined		10
	740					
	940					

Table 9-2 High-accuracy Grade (H)

Model No.	Rail Length	Positioning Repeatability	Positioning Accuracy	Running of Parallelism	Backlash	Starting Torque (N-cm)	
	150						
	200		0.060				
	300			0.025	0.020		
SKR33	400	± 0.005				7	
	500		0.100	0.035			
	600		0.100	0.000			
	700		0.120	0.040			
	340						
	440						
SKD46	540	± 0.005	0.100	0.035	0.020	10	
35540	SKR46 640 ± 0				0.020	10	
	740		0.120	0.040			
	940		0.150	0.050			

Unit: mm

Table 9-3 Precision Grade (P) Unit: n										
Model No.	Rail Length	Positioning Repeatability	Positioning Accuracy	Running of Parallelism	Backlash	Starting Torque (N-cm)				
	150									
	200									
	300		0.020	0.010						
SKR33	400	± 0.003			0.003	15				
	500		0.025	0.015						
	600		0.025	0.015						
	700		0.030	0.020						
	340									
	440		0.025	0.015		15				
SKR46	540	± 0.003	0.020	0.010	0.003					
	640					17				
	740		0.030	0.020						

The evaluation method complies with THK standards.

The starting torque shows a value achieved when THK AFB-LF grease is used with the product.

If high-viscosity grease, such as vacuum grease or clean room grease, is used, there are cases where the criteria value is exceeded. In such a case, exercise care when selecting the motor.



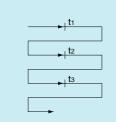
Accuracy Standards

The precision of the SKR is determined by repetitive positioning repeatability, positioning accuracy, backlash, and running parallelism.

Positioning Repeatability

Repeat the measurement seven times from the same direction to a certain point. Divide the maximum difference by two. Conduct the same test at three points, the "center" of the stroke, and on both the approximate maximum and minimum positions of travel. Add \pm to the largest difference. This accuracy is generally measured with a laser interferometer and sometimes with a dial-gauge.

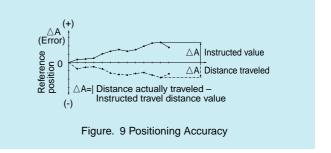
(Taken from THK Accuracy & Measurement Standards.)





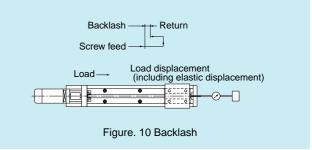
Positioning Accuracy

The maximum stroke is taken as the reference length, and the maximum error between the actual distance traveled from the reference position and the instructed value is expressed as an absolute value.



Backlash

Lock the actuator's carriage into a fixed position via the actuator's drive mechanism. Do not lock the actuator's carriage by "fixing" it rigidly. Push the carriage from one direction with a predetermined external force using a push/ pull gauge. Zero out the dial-gauge while the axial force is being applied-release the external force and read the dial-gauge. Measure at three separate points along the stroke, at the center and the end of travel positions. Backlash is the maximum measured value.



Running of Parallelism

A straightedge is placed on a leveling plate mounted with the SKR, and parallelism is measured over almost the entire distance traveled using a test indicator. The maximum error in the reading within the distance traveled is taken as the measurement value.

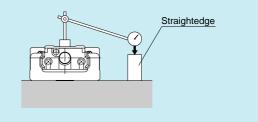


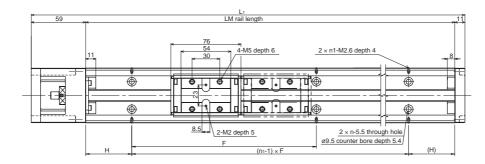
Figure. 11 Running of Parallelism

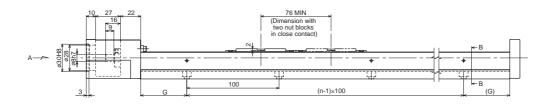


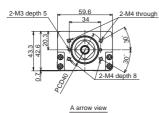
SKR33 Standard Type

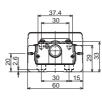
SKR33 C A (with a Single Long Block)

SKR33 🔲 B (with Two Long Blocks)





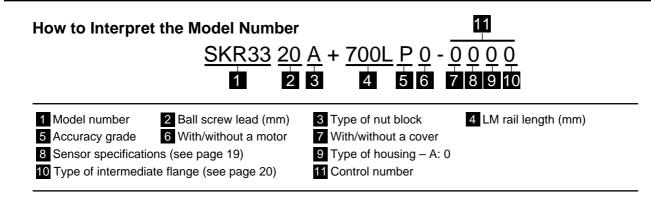




B - B cross section

LM Rail Overall Available Stroke Range (mm) Overall main unit mass (kg) Н G F Length L1 (mm) n n1 Length (mm) (mm) (mm) Type A Type B Type A Type B (mm) 1.7 2.1 2.8 3.1 3.5 3.8 4.2 4.5 5.0 5.3 5.7 6.0

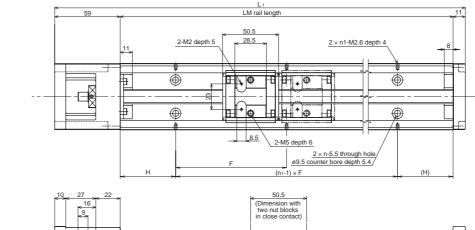
The available stroke range of SKR33 B shows a value applicable when the product is used with two long type blocks closely linked together.

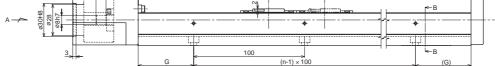


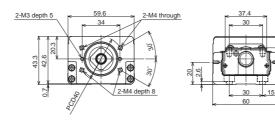


SKR33 C (with a Single Short Block)

SKR33 D (with Two Short Blocks)







A arrow view

B - B cross section

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LM Rail Length	Overall Length	Available Strok	e Range (mm)	Н	G	F	n	n1	Overall main	unit mass (kg)
(mm)	La (mm)	Туре С	Type D	(mm)	(mm)	(mm)	11	111	Туре С	Type D
150	220	80.5	30	25	25	100	2	2	1.6	1.8
200	270	130.5	80	50	50	100	2	2	2.0	2.1
300	370	230.5	180	50	50	200	3	2	2.7	2.8
400	470	330.5	280	100	50	200	4	2	3.4	3.6
500	570	430.5	380	50	50	200	5	3	4.1	4.3
600	670	530.5	480	100	50	200	6	3	4.8	5.0
700	770	630.5	580	50	50	200	7	4	5.5	5.7

The available stroke range of SKR33 D b shows a value applicable when the product is used with two short type blocks closely linked together.

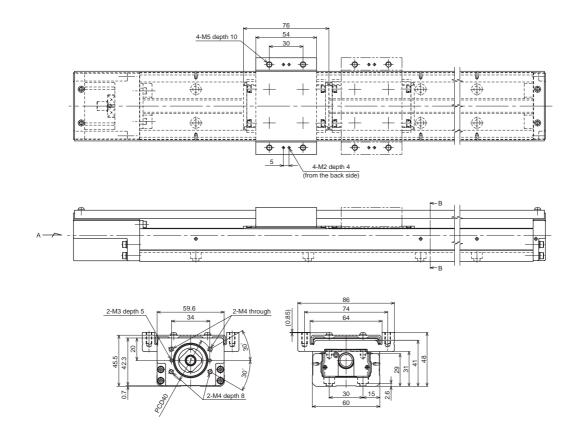
5 Accuracy	Description	Normal grade	High-accu	racy grade	Precision grade
grade	Symbol	No Symbol	ŀ	4	Р
6 Provision	Description	Not provided		Provid	ed (assembled at THK)
of Motor	Symbol	0			1
7 Provision	Description	Not provided			Provided
of Cover	Symbol	0			1



SKR33 A (with a Single Long Block)

SKR33 (with the Cover)

SKR33 🔲 B (with Two Long Blocks)

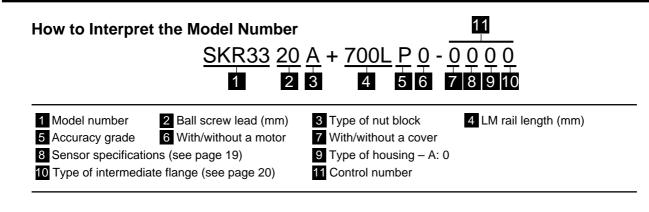


LM Rail Length	Overall Length	Available Strok	ke Range (mm)	Н	G	F	n	n1	Overall main	unit mass (kg)
(mm)	L1 (mm)	Туре А	Туре В	(mm)	(mm)	(mm)	11		Type A	Туре В
150	220	55		25	25	100	2	2	1.9	
200	270	105		50	50	100	2	2	2.3	
300	370	205	129	50	50	200	3	2	3.1	3.5
400	470	305	229	100	50	200	4	2	3.8	4.2
500	570	405	329	50	50	200	5	3	4.6	5.0
600	670	505	429	100	50	200	6	3	5.3	5.7
700	770	605	529	50	50	200	7	4	6.1	6.5

A arrow view

B - B cross section

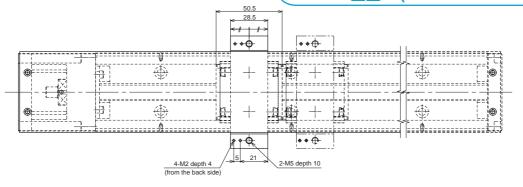
The available stroke range of SKR33 B shows a value applicable when the product is used with two long type blocks closely linked together.

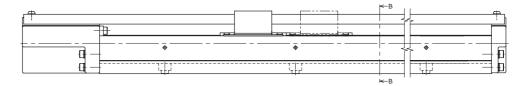


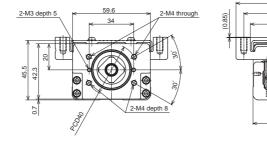


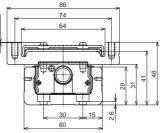
SKR33 C (with a Single Short Block)

SKR33 D (with Two Short Blocks)









A	arrow	view

B - B cross section

LM Rail Length	Overall	Available Strok	ke Range (mm)	Н	G	F	• . n		Overall main	unit mass (kg)
(mm)	Length L₁ (mm)	Type C	Type D	(mm)	(mm)	(mm)	11	n1	Туре С	Type D
150	220	80.5	30	25	25	100	2	2	1.8	2.0
200	270	130.5	80	50	50	100	2	2	2.2	2.3
300	370	230.5	180	50	50	200	3	2	2.9	3.1
400	470	330.5	280	100	50	200	4	2	3.7	3.8
500	570	430.5	380	50	50	200	5	3	4.4	4.6
600	670	530.5	480	100	50	200	6	3	5.2	5.3
700	770	630.5	580	50	50	200	7	4	5.9	6.1

The available stroke range of SKR33 D bhows a value applicable when the product is used with two short type blocks closely linked together.

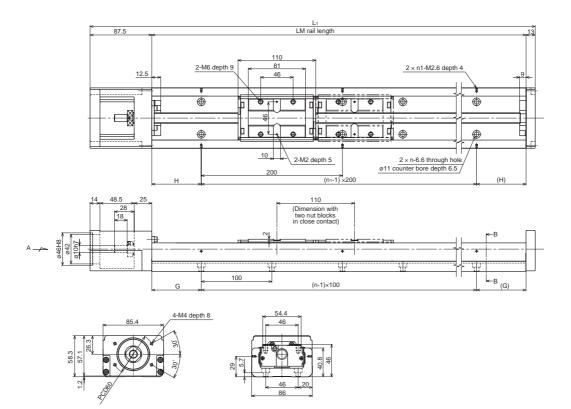
5 Accuracy	Description	Normal grade	High-accu	racy grade	Precision grade		
grade	Symbol	No Symbol	ŀ	4	Р		
6 Provision				Provid	ded (assembled at THK)		
of Motor	Symbol	0			1		
7 Provision	Description	Not provided			Provided		
of Cover	Symbol	0			1		

SKR46 Standard Type

A arrow view

SKR46 C A (with a Single Long Block)

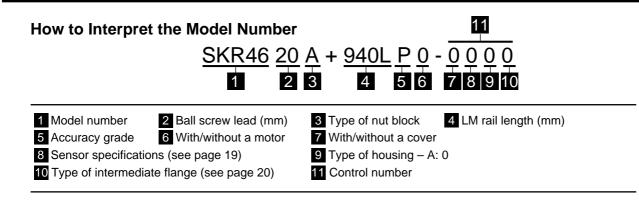
SKR46 🗌 B (with Two Long Blocks)



LM Rail	Overall	Available Strol	ke Range (mm)	Н	G	n	n1	Overall main	unit mass (kg)
Length (mm)	Length L₁ (mm)	Туре А	Туре В	(mm)	(mm)		111	Туре А	Туре В
340	440.5	208.5	98.5	70	70	3	2	6.4	7.4
440	540.5	308.5	198.5	20	70	4	3	7.8	8.7
540	640.5	408.5	298.5	70	70	5	3	9.2	10.1
640	740.5	508.5	398.5	20	70	6	4	10.6	11.5
740	840.5	608.5	498.5	70	70	7	4	12.0	12.9
940	1040.5	808.5	698.5	70	70	9	5	14.8	15.7

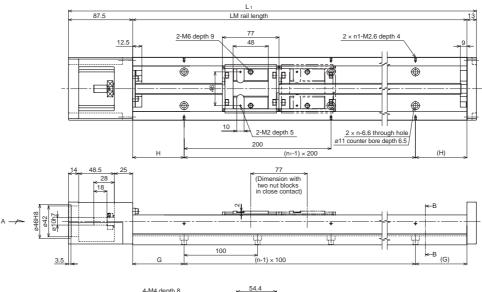
B - B cross section

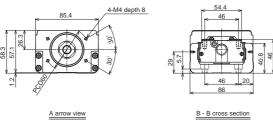
The available stroke range of SKR46 B shows a value applicable when the product is used with two long type blocks closely linked together.





SKR46 D (with Two Short Blocks)





LM Rail	Overall	Available Strok	ke Range (mm)	н	G	n	n1	Overall main	unit mass (kg)
Length (mm)	Length L₁ (mm)	Туре А	Туре В	(mm)	(mm)		111	Туре А	Туре В
340	440.5	241.5	164.5	70	70	3	2	6.1	6.7
440	540.5	341.5	264.5	20	70	4	3	7.5	8.1
540	640.5	441.5	364.5	70	70	5	3	8.9	9.5
640	740.5	541.5	464.5	20	70	6	4	10.3	10.8
740	840.5	641.5	564.5	70	70	7	4	11.7	12.2
940	1040.5	841.5	764.5	70	70	9	5	14.5	15.0

The available stroke range of SKR46 D b shows a value applicable when the product is used with two short type blocks closely linked together.

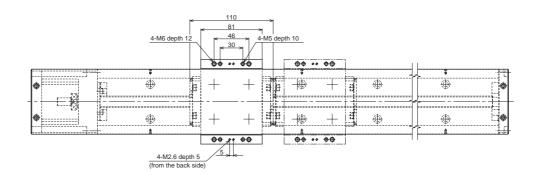
5 Accuracy	Description	Normal grade	High-accur	acy grade	Precision grade			
grade	Symbol	No Symbol	F	1	Р			
6 Provision	Description	Not provided		Provided (assembled at THK)				
of Motor	Symbol	0			1			
7 Provision					Provided			
of Cover	Symbol	0			1			

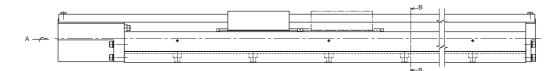


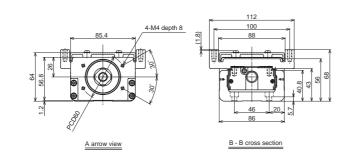
SKR46 C A (with a Single Long Block)

SKR46 (with the Cover)

SKR46 🔲 B (with Two Long Blocks)

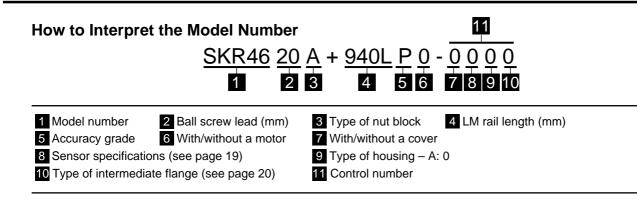






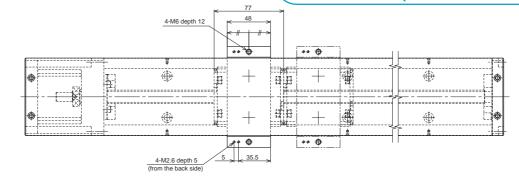
	Rail	Overall	Available Strok	e Range (mm)	н	G	n	n1	Overall main	unit mass (kg)
	ngth nm)	Length L₁ (mm)	Туре А	Туре В	(mm)	(mm)		111	Туре А	Туре В
34	10	440.5	208.5	98.5	70	70	3	2	7.1	8.3
44	10	540.5	308.5	198.5	20	70	4	3	8.6	9.8
54	10	640.5	408.5	298.5	70	70	5	3	10.0	11.3
64	10	740.5	508.5	398.5	20	70	6	4	11.5	12.7
74	10	840.5	608.5	498.5	70	70	7	4	13.0	14.2
94	10	1040.5	808.5	698.5	70	70	9	5	16.0	17.2

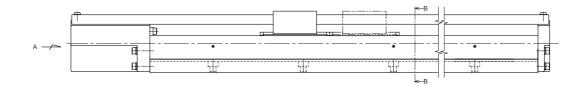
The available stroke range of SKR46 B shows a value applicable when the product is used with two long type blocks closely linked together.



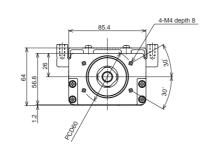
SKR46 C (with a Single Short Block)

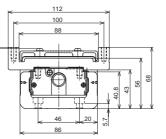
SKR46 C D (with Two Short Blocks)





(1.8)





		A arrow view			B - B cross se	ection			
LM Rail Length	Overall Length	Available Stroke Range (mm)		н	G	n	n1	Overall main	unit mass (kg)
(mm)	Length L1 (mm)	Туре С	C Type D (mm) (mm)		(mm)		111	Туре С	Type D
340	440.5	241.5	164.5	70	70	3	2	6.6	7.4
440	540.5	341.5	264.5	20	70	4	3	8.1	8.9
540	640.5	441.5	441.5 364.5		70	5	3	9.6	10.3
640	740.5	541.5	464.5	20	70	6	4	11.0	11.8
740	840.5	641.5	564.5	70	70	7	4	12.5	13.3
940	1040.5	841.5	764.5	70	70	9	5	15.5	16.3

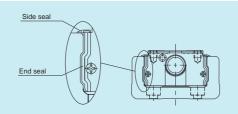
The available stroke range of SKR46 D b shows a value applicable when the product is used with two short type blocks closely linked together.

5 Accuracy			High-accu	racy grade	Precision grade		
grade	Symbol	No Symbol	ŀ	4	Р		
6 Provision	Description	Not provided		Provided (assembled at THK)			
of Motor	Symbol	0		1			
7 Provision					Provided		
of Cover	Symbol	0		1			





The SKR is equipped with an end seal and side seal as standard for dust-proofing.



Sensors

Proximity sensors and photosensors are available as options for the SKR33 and SKR46. When a customer specifies a model with a sensor, specially designed sensor rails and sensor dogs are supplied with the product.

Sensor Specifications

Symbol	Description	Туре	Accessory
0	None	-	-
1	With sensor rail	-	Mounting screw
2	3 photosensors	EE-SX671 (OMRON)	Mounting screw/nut, detecting plate, sensor rail, mounting plate, connector (EE-1001)
4	3 proximity sensors Normally OPEN	GL-12F (SUNX)	Mounting screw/nut, detecting plate, sensor rail, fixture (MS-GL12)
5	3 proximity sensors Normally OPEN	GXL-N12F (SUNX)	Mounting screw/nut, detecting plate, sensor rail, fixture (MS-GXL12)
6	3 photosensors	EE-SX674 (OMRON)	Mounting screw/nut, detecting plate, sensor rail, mounting plate, connector (EE-1001)
7	3 proximity sensors Normally OPEN	APM-D3A1-001(YAMATAKE)	Mounting screw/nut, detecting plate, sensor rail
8	3 proximity sensors Normally OPEN	GL-N12F (SUNX)	Mounting screw/nut, detecting plate, sensor rail
9	3 proximity sensors Normally CLOSED	GL-N12FB (SUNX)	Mounting screw/nut, detecting plate, sensor rail
A	3 proximity sensors Normally CLOSED	GXL-N12FB (SUNX)	Mounting screw/nut, detecting plate, sensor rail, fixture (MS-GXL12)
В	3 proximity sensors Normally CLOSED	APM-D3B1-003(YAMATAKE)	Mounting screw/nut, detecting plate, sensor rail
С	Proximity sensor Normally OPEN (1), Normally CLOSED (2)	GL-N12F (1 unit), GL-N12FB (2 units)	Mounting screw/nut, detecting plate, sensor rail
D	Proximity sensor Normally OPEN (1), Normally CLOSED (2)	GXL-N12F (1 unit), GXL-N12FB (2 units)	Mounting screw/nut, detecting plate, sensor rail, fixture (MS-GXL12)
E	Proximity sensor Normally OPEN (1), Normally CLOSED (2)	APM-D3A1-001 (1 unit), APM-D3B1-003 (2 units)	Mounting screw/nut, detecting plate, sensor rail
F	Proximity sensor Normally OPEN (1), Normally CLOSED (2) (PNP OUTPUT)	GXL-N12F-P (1 unit), GXL-N12FB-P (2 units)	Mounting screw/nut, detecting plate, sensor rail, fixture (MS-GXL12)

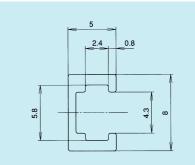


Sensors

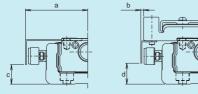
Proximity sensors	GL-N12F (B) (SUNX)	3 units 3 units
	GXL-N12F (B) (SUNX)	3 units
	APM-D3A1-001 (Yamatake)	3 units
	(APM-D3B1-003)	
Photosensors	EE-SX671 (OMRON)	3 units
	EE-SX674 (OMRON)	3 units
Connectors	EE-1001 (OMRON)	3 units
Note: Connectors	come as standard with photose	ensors.

Sensor rails

It is also possible to install a sensor rail only.

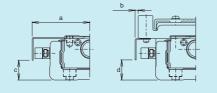


Proximity sensors GL-12F, GL-N12F (B), and GXL-N12F (B) (SUNX)



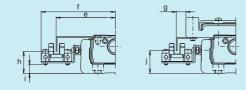
			ι	Jnit: mm
Model	а	b	С	d
SKR33	44.7	2	13.8	14
SKR46	57.7	1.8	24.8	22

Proximity sensors APM-D3A1 and APM-D3B1 (Yamatake)



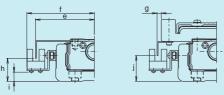
Unit: mm										
Model	а	b	С	d						
SKR33	43.05	0.3	14.8	15						
SKR46	56.2	0.2	26.8	22						

Photosensor EE-SX671 (OMRON)



					ι	Jnit: mm
Model	е	f	g	h	i	j
SKR33	51.1	63.6	8.3	18.8	7.4	19.5
SKR46	64.1	76.6	8.3	29.8	16.4	26.5

Photosensor EE-SX674 (OMRON)



					ι	Jnit: mm
Model	е	f	g	h	i	j
SKR33	45.9	52.1	3.3	17.8	7.1	20
SKR46	58.9	65.1	3.2	28.8	16.1	27



Intermediate Flanges

Applicable Motors and Applicable Intermediate Flanges

The SKR-type is provided with intermediate flanges so that a variety of motors can be installed. The table below shows the control number of the intermediate flanges meeting the applicable motors on a model number basis. At the time of order, specify the intermediate flange control number.

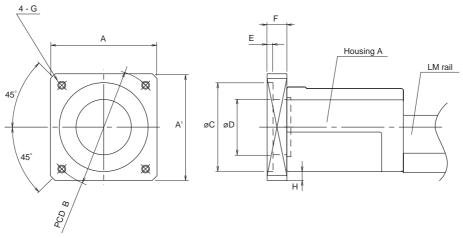
		ſ	Notor	model No.	Flange angle	SKR33	SKR46
	<u>.0</u>			SGMAH-A3 (30W)	0.00	OH	0F
	Yaskawa Electric			SGMAH-A5 (50W)	□40	OH	0F
	Ш	Ц	╡	SGMAH-01 (100W)		ОН	0F
	wa			SGMPH-01 (100W)		_	04
	ska			SGMAH-02 (200W)	□60	_	04
	Ya			SGMAH-04 (400W)		_	04
				HC-MFS 053 (50W)		ОН	0F
	ric			HC-KFS 053 (50W)		ОН	0F
	ect	9	5	HC-MFS 13 (100W)	- 🗌 40 -	ОН	0F
	Ē	MELSERVO	Super	HC-KFS 13 (100W)		ОН	0F
	ish	N.	ິດ	HC-MFS 23 (200W)		_	04
	qn	1EL	J2	HC-KFS 23 (200W)		_	04
	Mitsubishi Electric MELSERVO J2 Super			HC-MFS 43 (400W)	- 🗌 60 -	_	04
	2			HC-KFS 43 (400W)	1 1	_	04
	ic			MSMA 3A (30W)		0K	0G
5	Matsushita Electric	<	c	MSMA 5A (50W)	□38	0K	0G
oto	ы Ш	MINIASA	2	MSMA 01 (100W)		0K	0G
Ű.	shita			MQMA 01 (100W)		_	03
Servomotor	tsus		2	MSMA 02 (200W)	□60	_	03
Ň	Ma			MSMA 04 (400W)		_	03
	ĽĊ.	10	ž	Q1AA04003D (30W)		0H	0F
	SANYO Electric		5	Q1AA04005D (50W)	□40	0H	0F
	ΞO	UTC	-	Q1AA04010D (100W)		0H	0F
	Х			Q1AA06020D (200W)		_	04
	SAI	V V	5	Q1AA06040D (400W)	- 🗌 60 -	_	04
		,	>	R88M-W03030 (30W)		0H	0F
	OMRON		>)	R88M-W05030 (50W)	□40	0H	0F
	1R(Ś	R88M-W10030 (100W)		0H	0F
	õ		No.	R88M-W20030 (200W)	60 -	-	04
		C		R88M-W40030 (400W)		-	04
			0	β0.2/5000is (50W)	40	ОH	0F
	<u>0</u>	ooijoo	کا ا	β0.3/5000is (100W)	LI40	0H	0F
	Fanuc	03	Do	β0.4/5000is (125W)		_	04
	Ш	<u>, 0</u>	<u>e</u>	β0.5/5000is (200W)	□60	_	04
				β1/5000is (400W)		-	04
		∽Cton	<u>с</u>	AS 46, ASC46	42	01	_
or	F	Ŭ Z	2	AS 6□, ASC66	□60	0G	01
Stepping motor	Oriental Motor	5 phase	ХX	RK54	42	01	_
lg r	Σ	5 pł		RK56	□60	0G	01
pin	nta	e	UMK	UMK24	□42	01	-
tep	lrie	phase		UMK26	□56.4	0F	_
S	0	2 pł	YS:	CSK24	□42	01	_
			Ü	CSK26	□56.4	0F	-

Table11 Table of Motors Used and Corresponding Motor Brackets

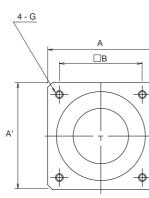
Note1) The symbols in the table each indicate the last two digits of an administration number. Note2) For the coupling for mounting a motor in the table, contact THK.

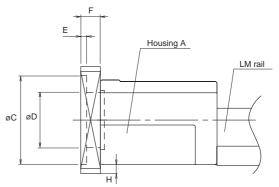


Dimensions of the Intermediate Flanges

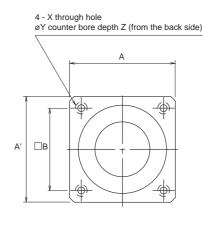


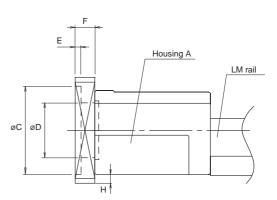
	Control number	A × A'	В	С	D	E	F	G	Н
	0B	54 × 54	60	50	28	3	10	M4	4
SKR33	0H	42 × 40	46	30	28	3	10	M4	
	0K	42 × 38	45	30	28	3.5	10	M3	
	02	62 × 60	60	50	42	3.5	10	M4	
	03	62 × 60	70	50	42	3.5	10	M4	
SKD46	04	62 × 60	70	50	42	4	10	M5	
SKR46	0A	76 × 76	90	70	42	3.5	12	M5	6
	0F	62 × 53	46	30	_		10	M4	_
	0G	62 × 53	45	30			10	M3	





	Control number	A × A'	В	С	D	E	F	G	Н
SKR33	0F	56.4×56.4	47.14	38.1	28	2	10	M4	5.2
35533	0G	60 × 60	50	36	28	2	10	M4	7
SKR46	01	62 × 60	50	36			10	M4	





	Control number	A × A'	В	С	D	E	F	Х	Y	Z
SKR33	01	42 × 42	31	22			7	3.5	6	4



行用 LM-Guide Actuator SKR-type

Precautions on Use

Handling

- Exercise care when handling the product. Dropping or tapping it may result in breakage.
- Do not disassemble the product unless it is unavoidable. Disassembling the product unnecessarily may result in the entry of foreign matter or cause accuracy degradation.
- Operating the product exceeding the permissible revolution speed may lead to part breakage or accidents. The operating revolution speed should be limited to the range specified by THK.

Operating temperature range

 The service temperature range of this product is 0 to 40°C (no freezing or condensation). If you consider using this product outside the service temperature range, contact THK.

Lubrication

- To deliver the full extent of SKR-type functions, lubrication is essential. Use of the product without lubrication may result in increased abrasion at the rolling section or shorter life.
- · Do not mix and use lubricants with different properties.
- The greasing intervals differ with the operating conditions. It is recommended that the greasing intervals be determined at the initial inspection.
- If the product is used in locations constantly exposed to vibration or in special environments such as clean rooms, vacuums, low temperatures, or high temperatures, there are cases where ordinary greases cannot be used. In such cases, contact THK.

Use and Lubrication in Special Environments

 If locations are constantly exposed to vibration or in special environments such as clean rooms, vacuums, low temperatures, or high temperatures, consult THK.

Safety precautions

- If the product is operating or in the ready state, never touch a moving part. In addition, do not enter the operating area of the actuator.
- If two or more people are involved in the operation, confirm the procedures such as a sequence, signs and anomalies in advance, and appoint another person for monitoring the operation.
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