

Power converters AC/DC and DC/AC - MM5

Thyristors

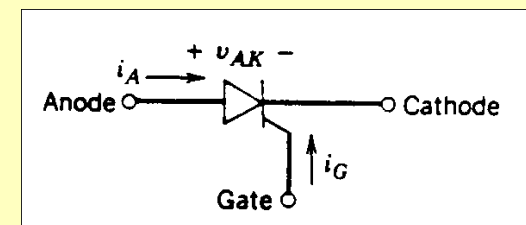
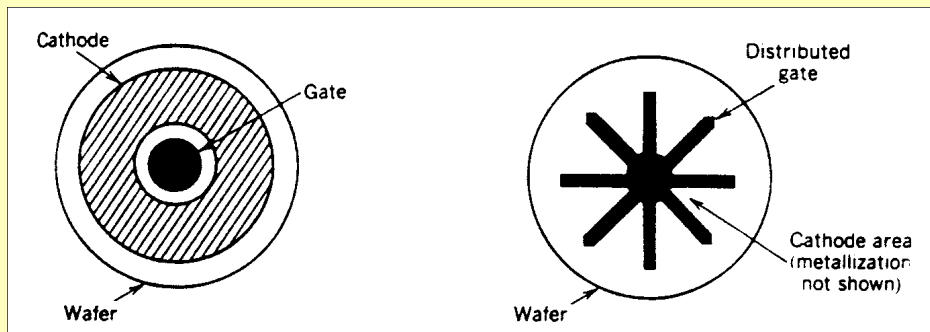
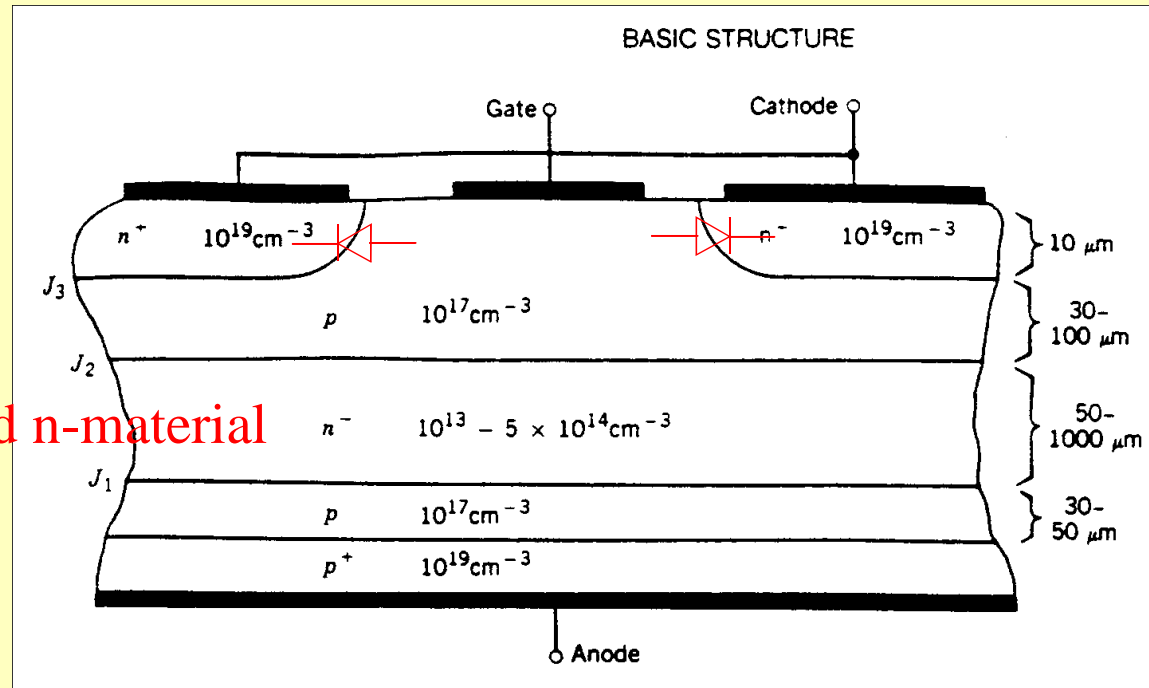
Content MM5

1. Summary from MM4
2. Thyristor working principle
3. Protection circuits
4. Drive circuits
5. Modeling reverse recovery
6. Exercises

Physical layout

2. Thyristor working principle

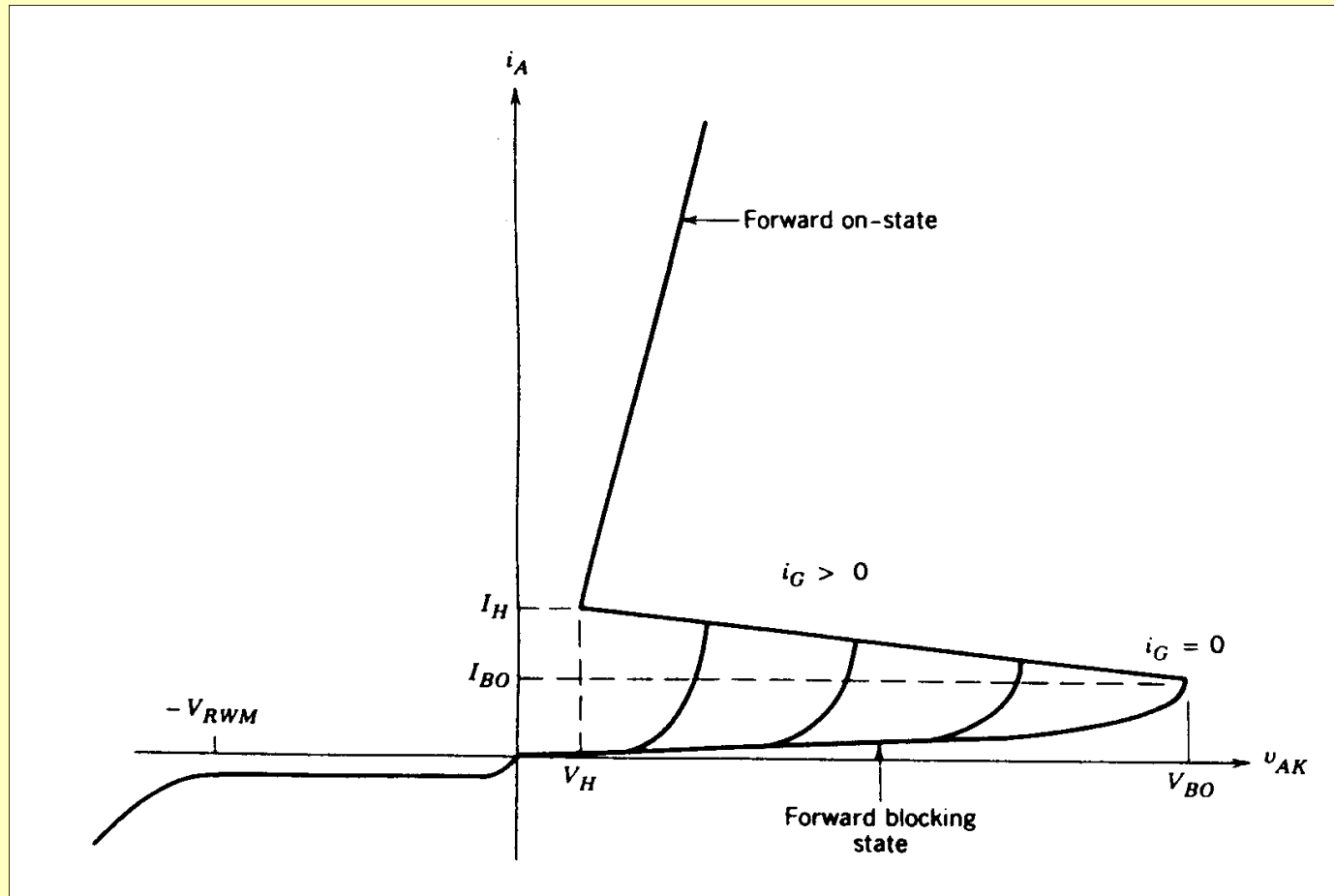
Lightly doped n-material



Symbol

2. Thyristor working principle

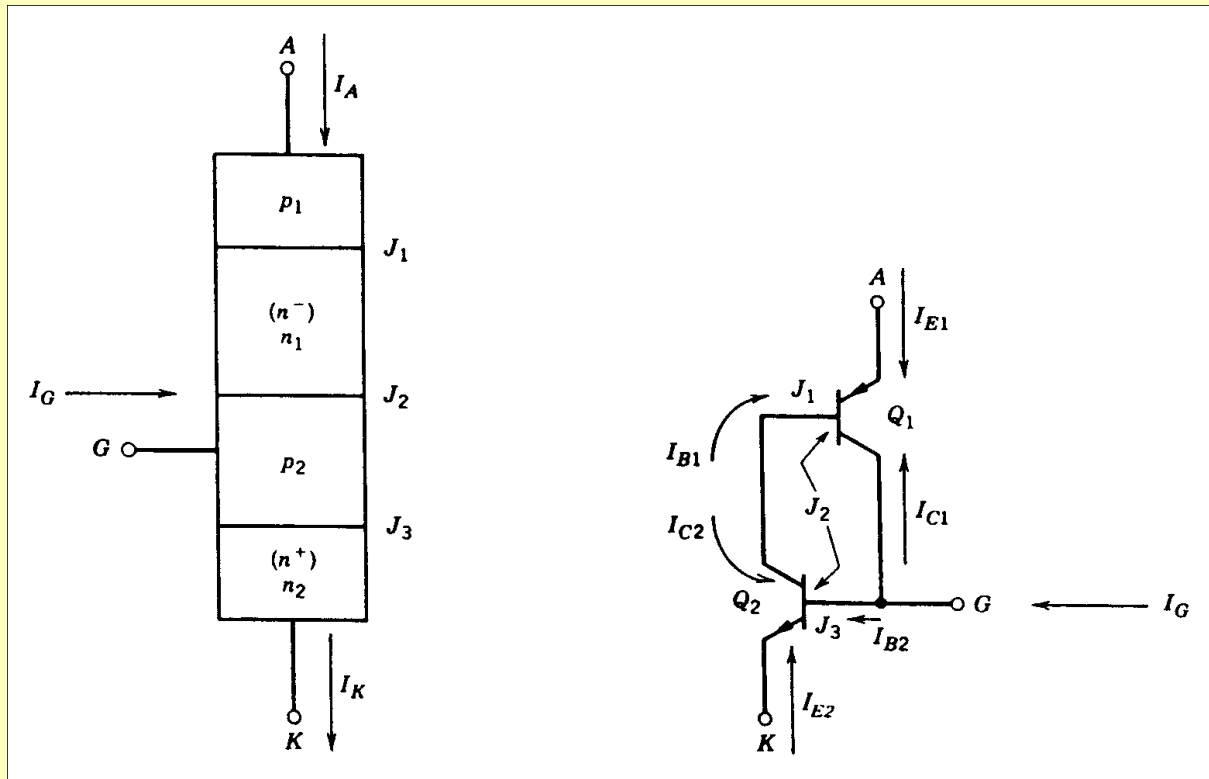
Static characteristic



$$-V_{RWM} \approx V_{BO}$$

2. Thyristor working principle

Model



Q1: $I_{C1} = -\alpha_1 I_{E1} + I_{CO1}$

Collector currents

Q2: $I_{C2} = -\alpha_2 I_{E2} + I_{CO2}$

$$I_{CO} = I_{CS}[1 - \alpha_f \alpha_r]$$

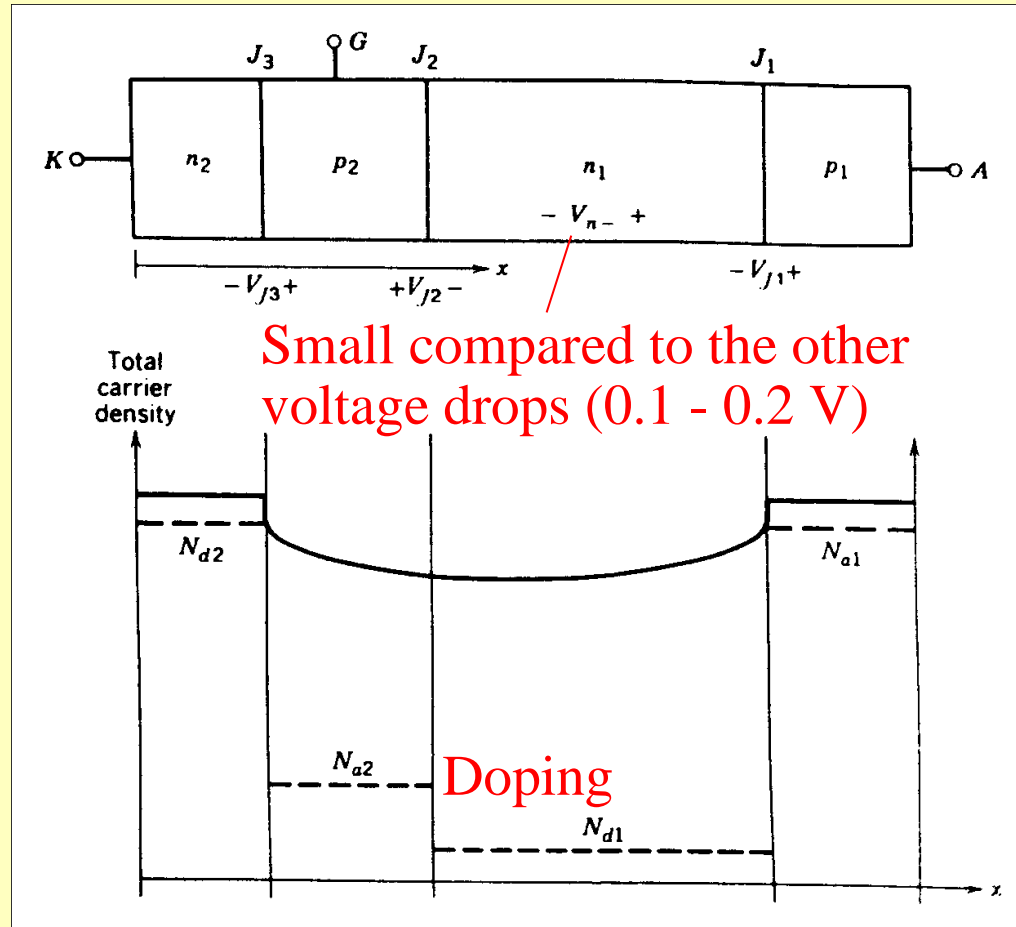
Leakage current

$$I_A = \frac{\alpha_2 I_G + I_{CO1} + I_{CO2}}{1 - (\alpha_1 + \alpha_2)}$$

$\alpha_1 + \alpha_2 \ll 1$ when off

2. Thyristor working principle

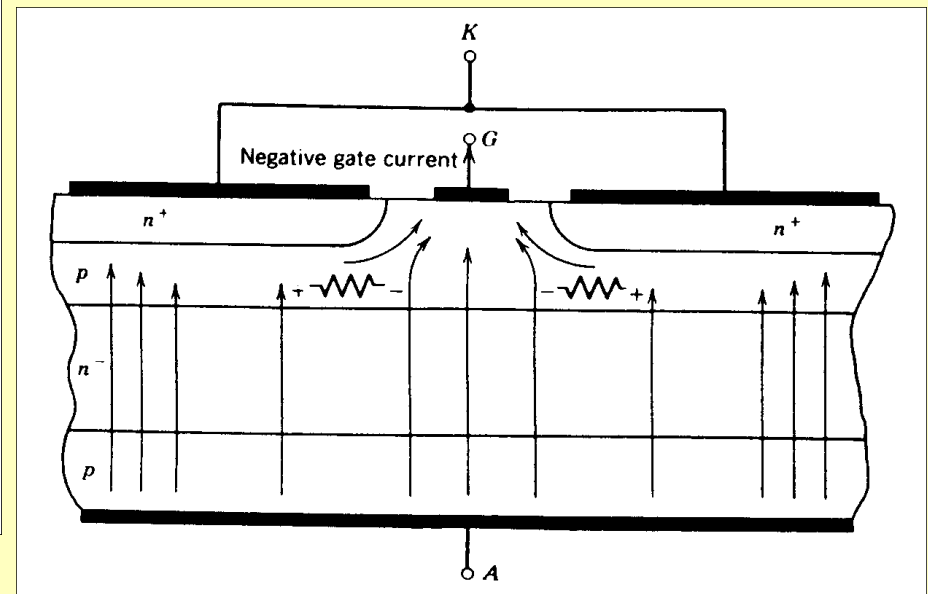
On-state



Voltage drop

$$V_{AK(on)} = V_{J1} - V_{J2} + V_{J3} + V_{n-}$$

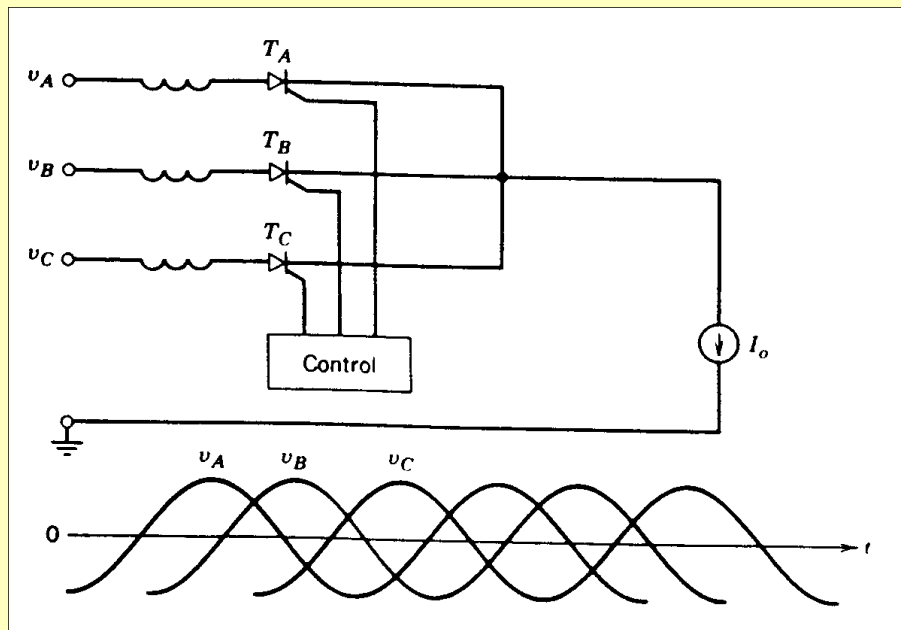
Attempted turn-off



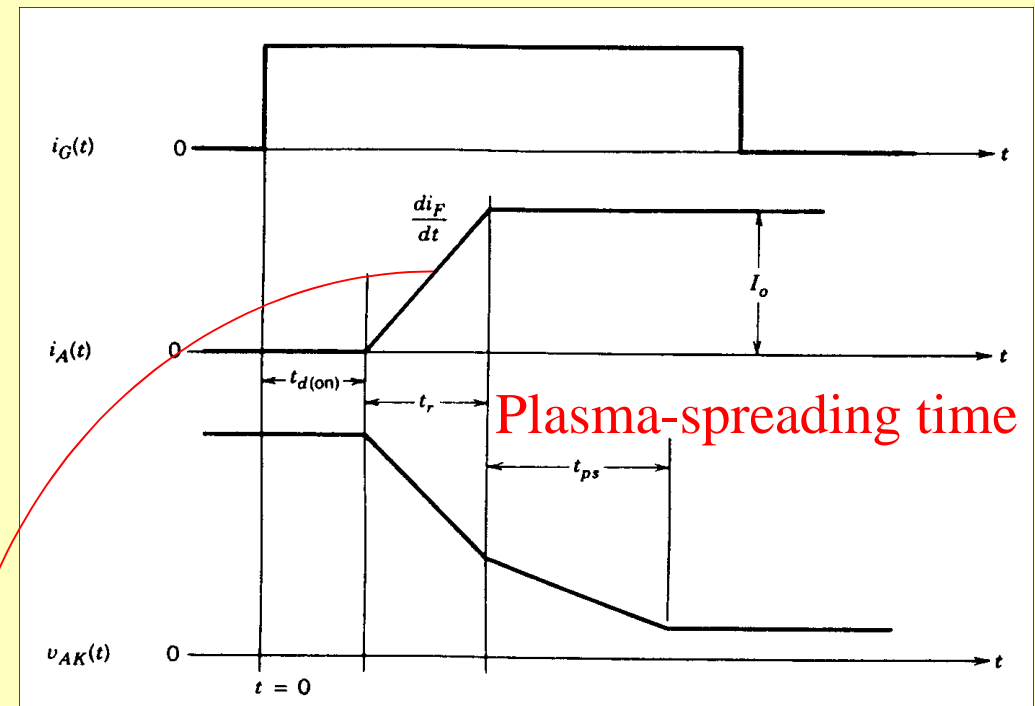
Negative gate current will make it difficult for the current to flow in the middle of the Thyristor. But the Thyristor will **not** turn-off.

2. Thyristor working principle

Turn-on



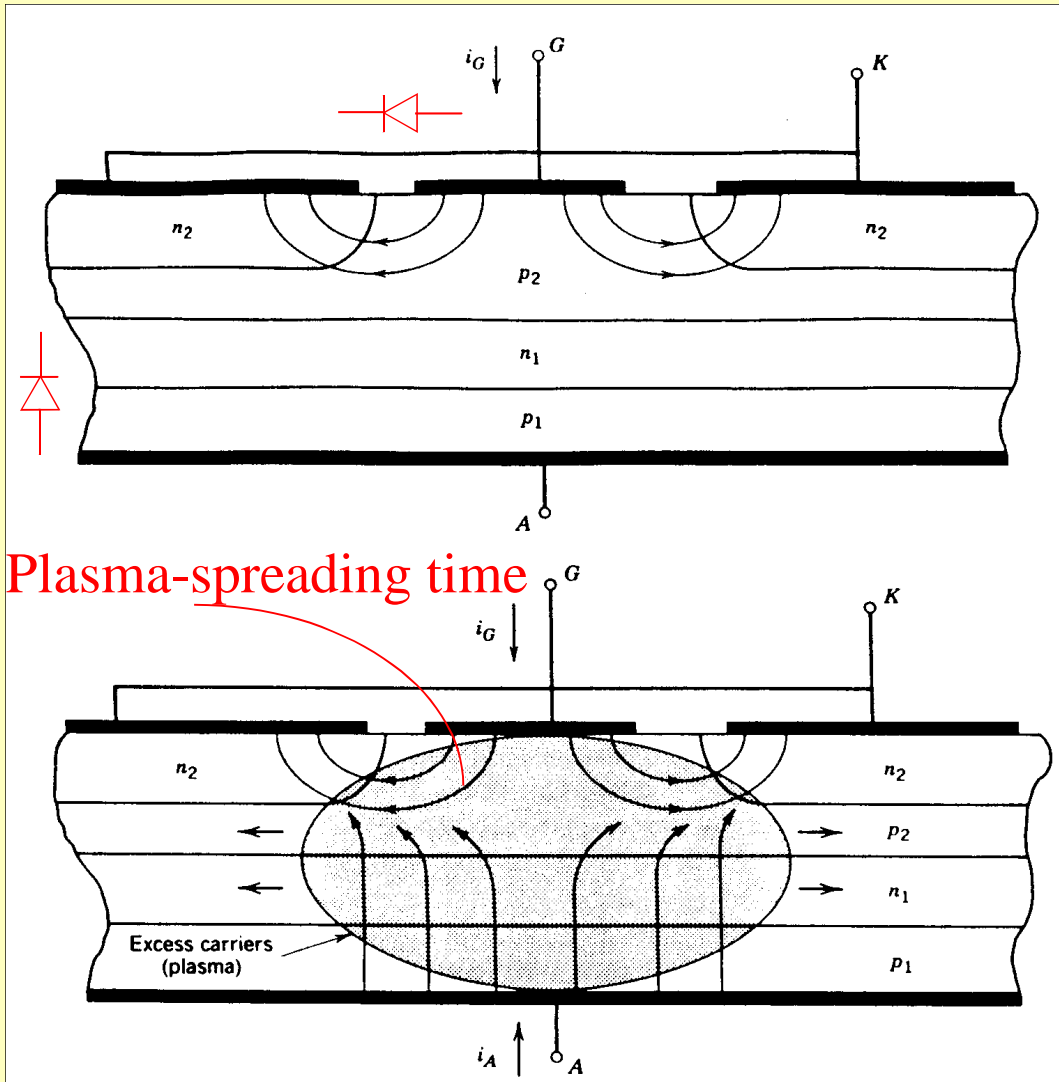
Voltage and current



Determined by the inductance in the circuit. Maximum value is often given in data-sheet.

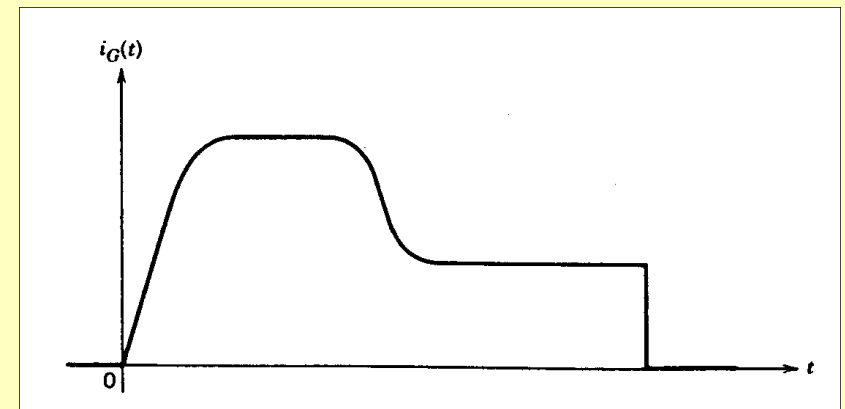
Controlled turn-on

2. Thyristor working principle



- Current amplification
- Large physical spreading

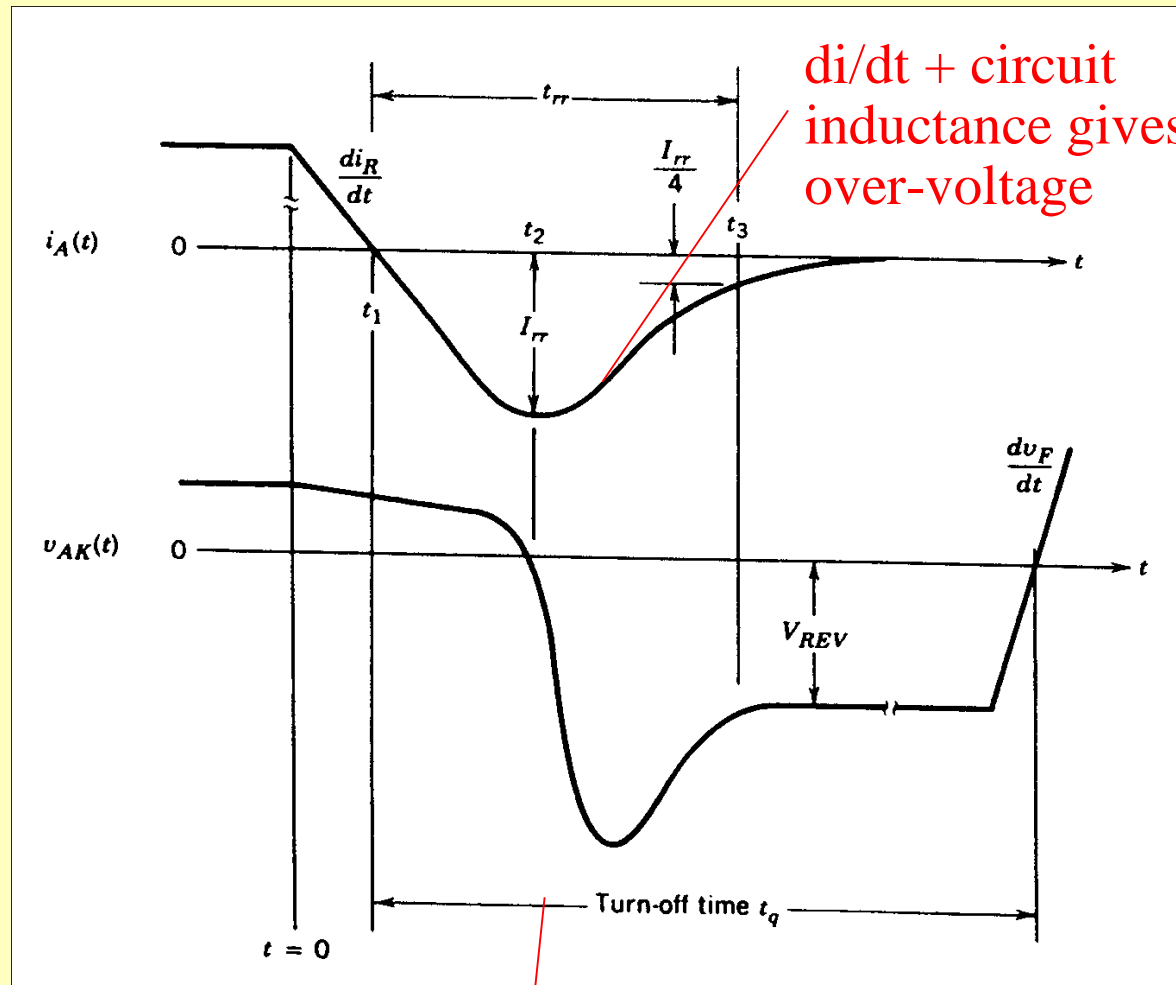
Gate current



Gate current with an initial large value in order to maximize the initial turn-on area.

2. Thyristor working principle

Turn-off



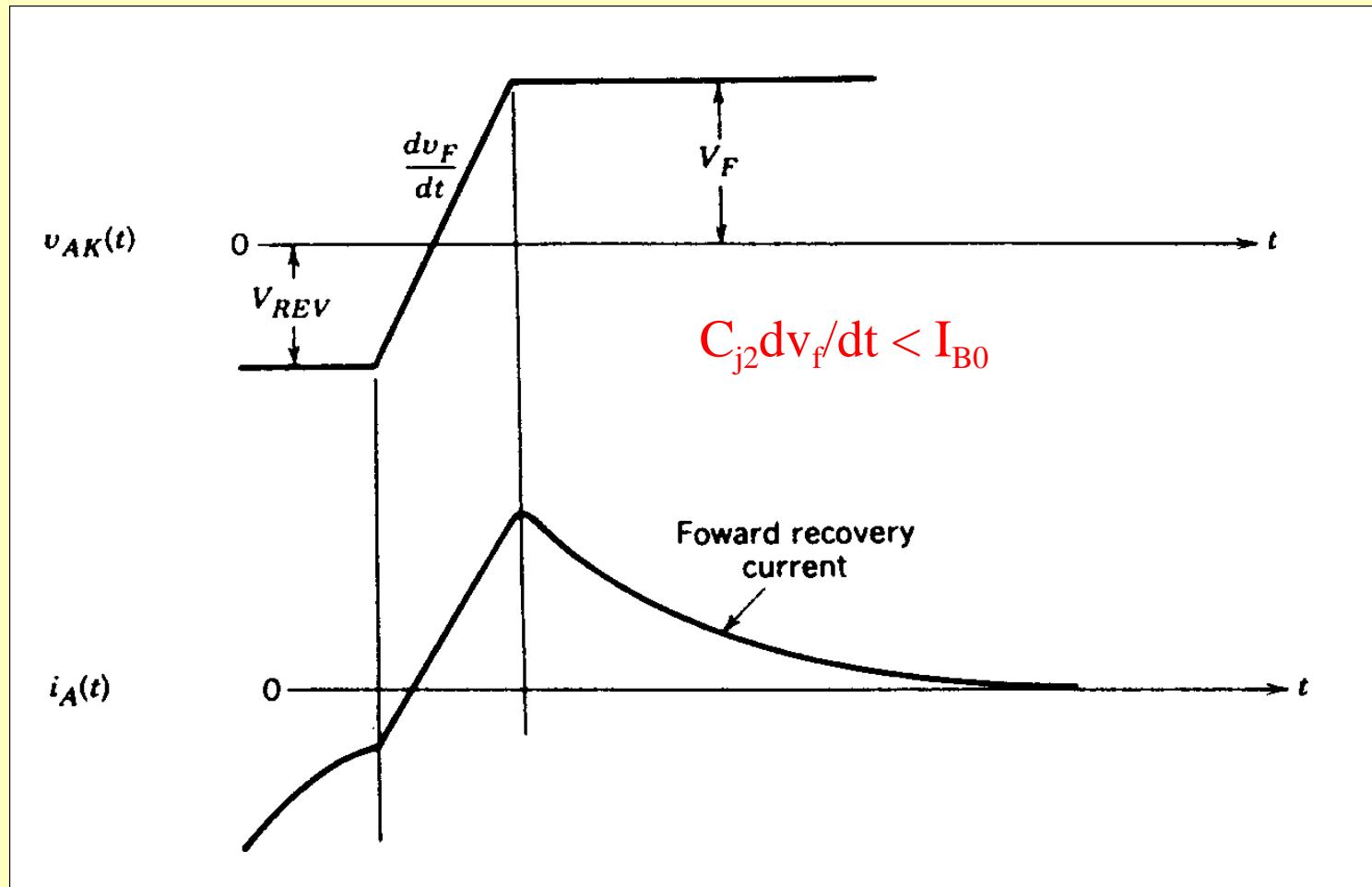
Notes

- di/dt determined by the circuit.
- Thyristor is first turned-off when the carriers in n^- layer is disappear.
- With decreasing current at turn-off is an over-voltage generated.
- $Q_{rr} = 1/2 t_{rr} I_{rr}$ is often listed in the data-sheet.
- Same characteristic for the diode.

No forward blocking voltage before the time is elapsed.

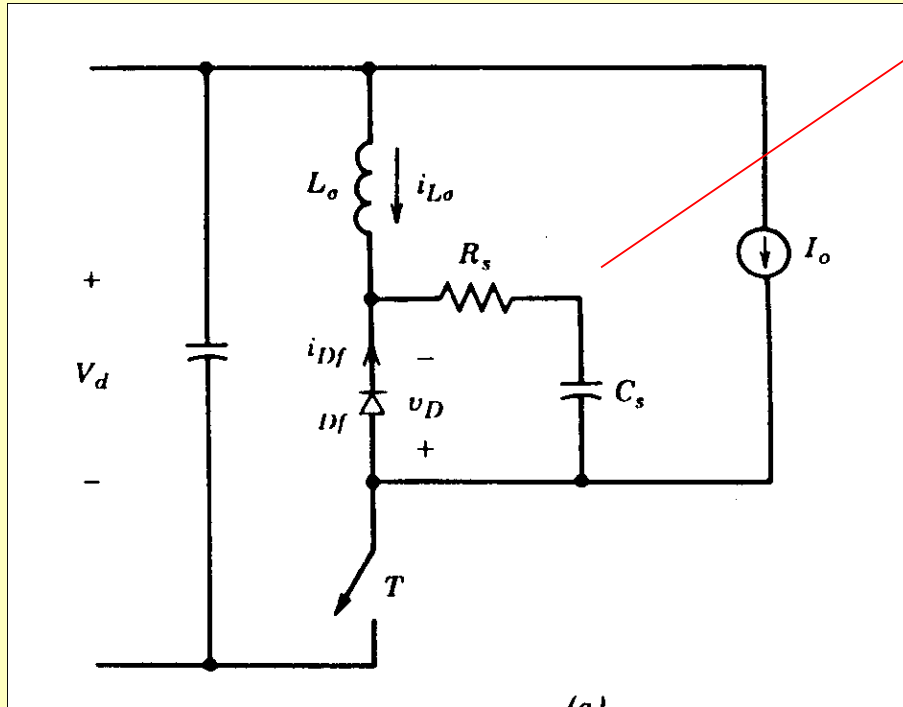
2. Thyristor working principle

Accidental turn-on due to dv/dt



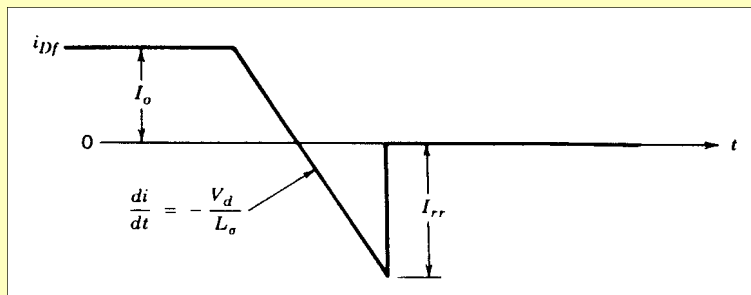
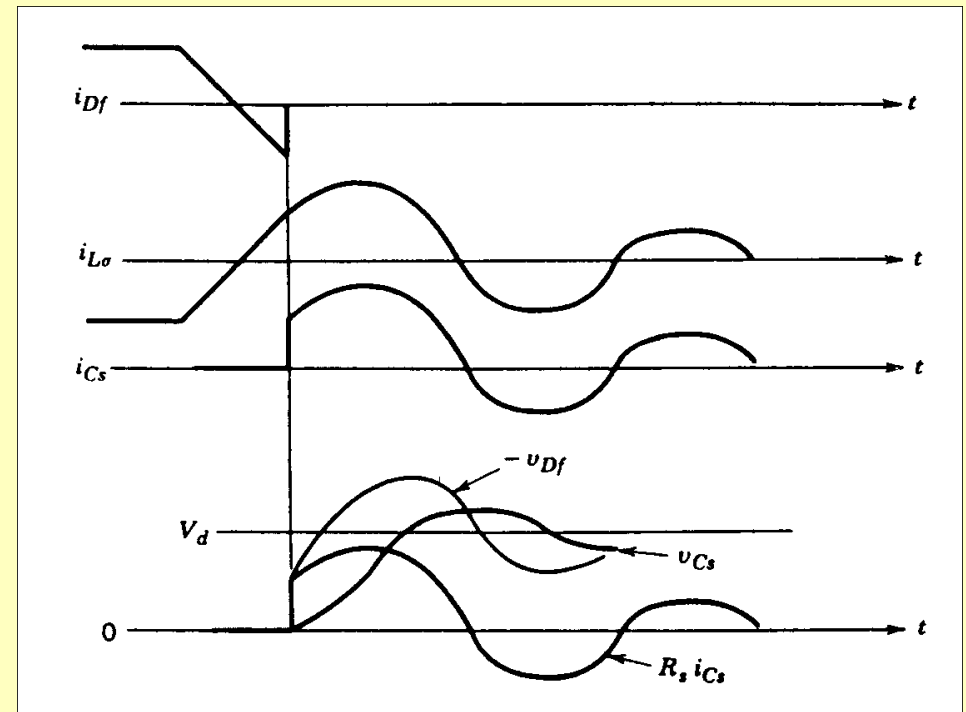
3. Protection circuits

Snubber circuits



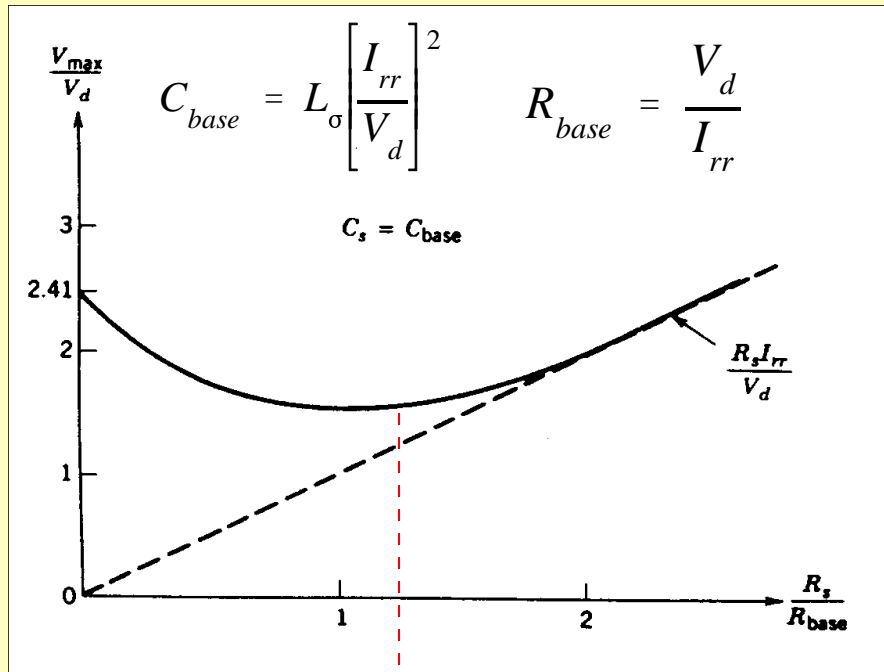
Over-voltage snubber / diode snubber

Snubber waveforms



3. Protection circuits

“Optimal” Snubbers

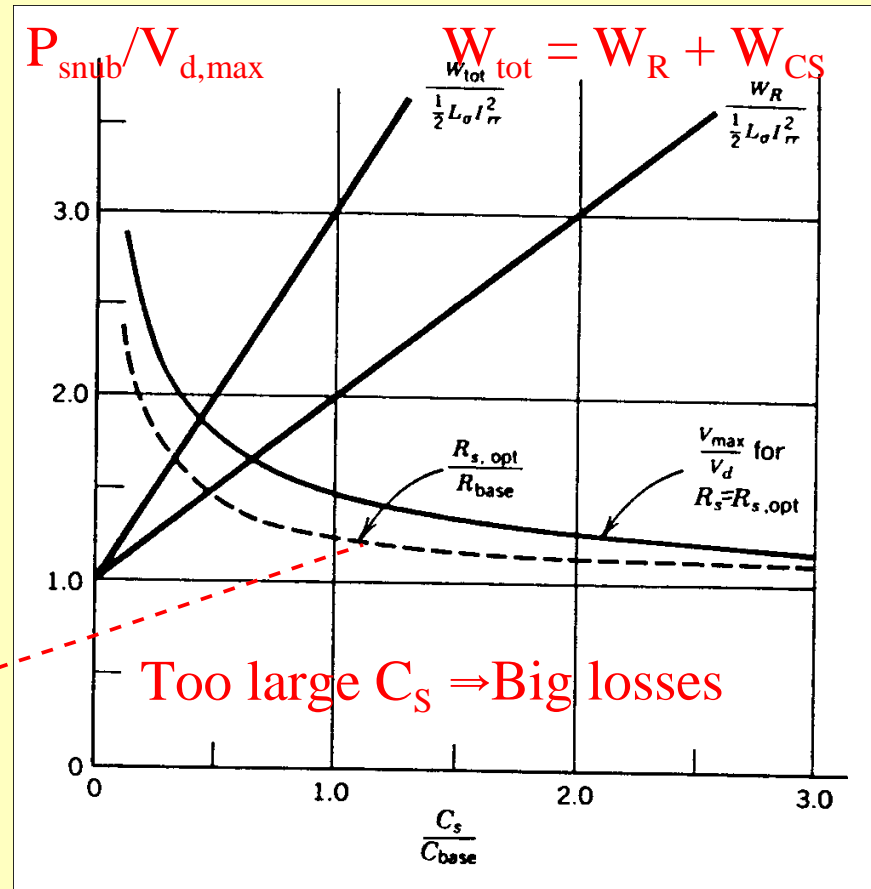


$R_s = R_{opt} = 1.3R_{base}$

Optimum for V_{max}

Determination of $R_{s,opt}$ when C_s is found

Characteristic



3. Protection circuits

Thyristors are sensitive

Causes :

- Too large currents and voltages
- Large mechanical construction

Limits :

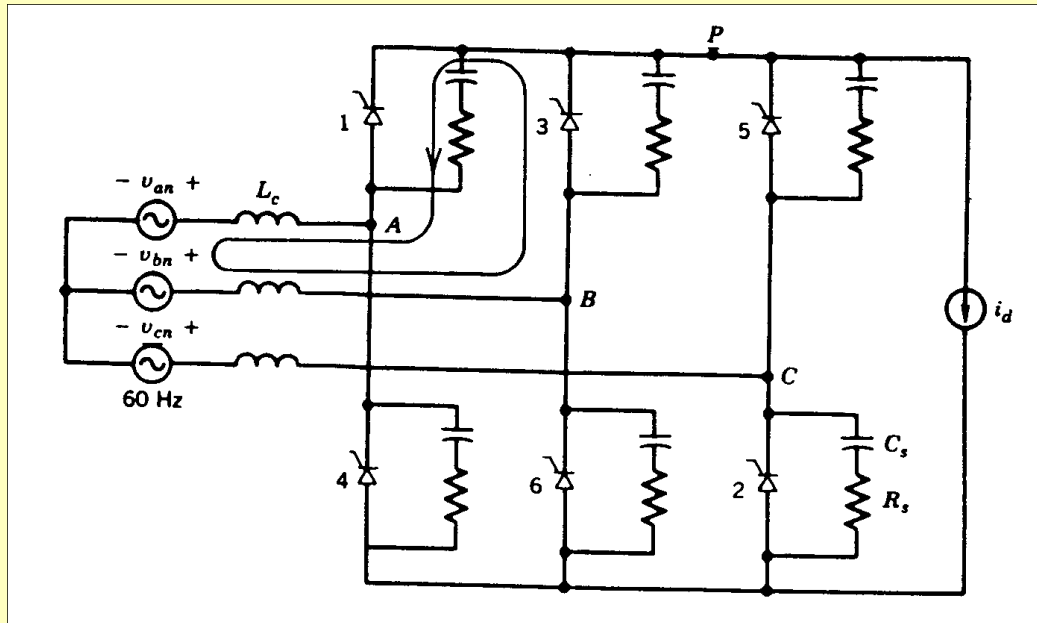
- di/dt_{on} (skin-effects)
- dv/dt (Internal capacitances can trig the Thyristor)
- Over voltages

⇒ Therefore Snubbers !

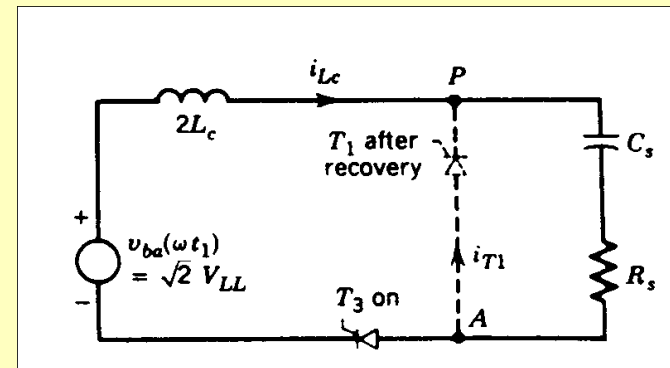
Now we will look on line-commutated Thyristor protection.

3. Protection circuits

Circuit



Equivalent circuit

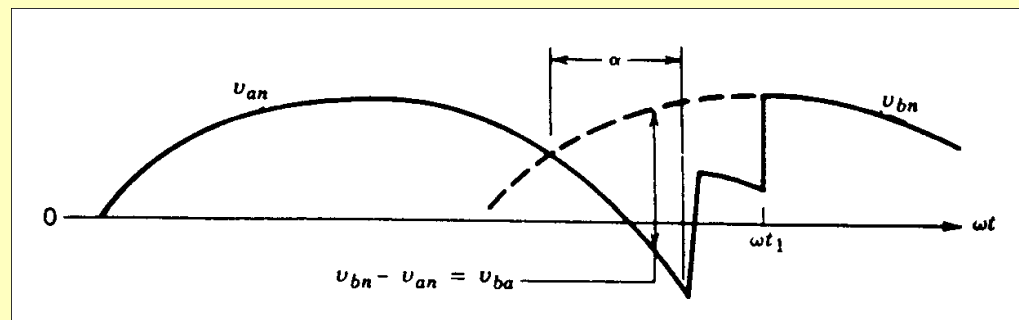


- L_c is line inductance \Rightarrow Limits di/dt
- R,C controls dv/dt and over voltage together with L_c
Worst case ($\alpha = 90^\circ$)

$$\frac{di}{dt} = \frac{\sqrt{2} V_{LL}}{2L_c}$$

If di/dt is too large an extra inductance must be added.

Waveforms



3. Protection circuits

Reverse recovery current

$$I_{rr} = \left(\frac{di}{dt} \right) \cdot t_{rr}$$

Energy in $2L_c$ is moved over in C

Reasonable guess

$$C = L_c \left(\frac{I_{rr}}{V_{LL}} \right)^2$$

Optimal choice of R

$$R = 1.3 \sqrt{2} \frac{V_{LL}}{I_{rr}}$$

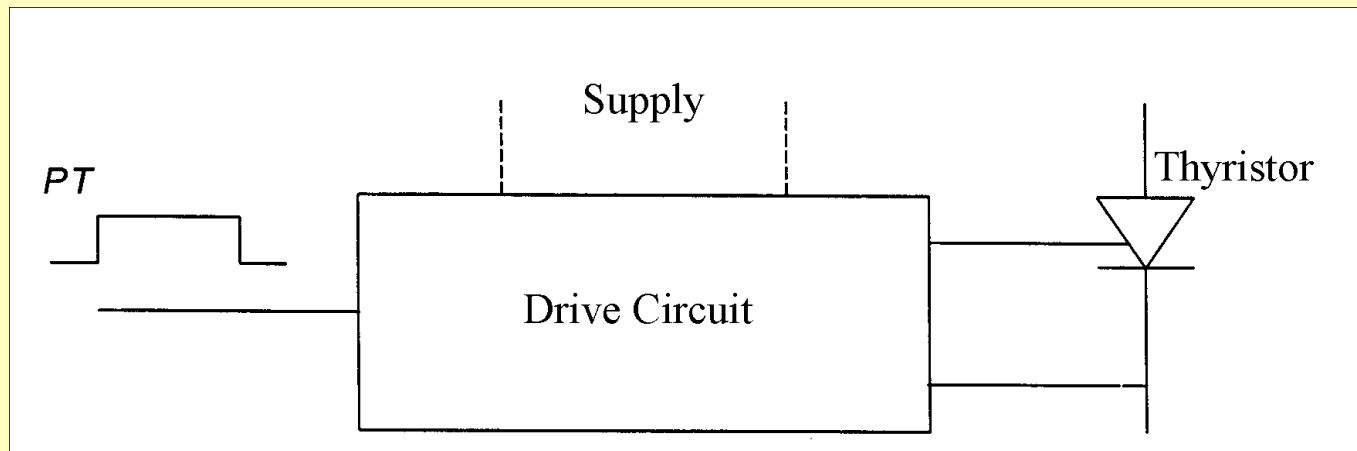
If R is large \Rightarrow Large over-voltage

If R is small \Rightarrow Large power losses

Choice of C and R is a compromise between power-loss and over-voltage. The given values is a good starting point for a optimization. dv/dt has also to be checked.

Drive circuit

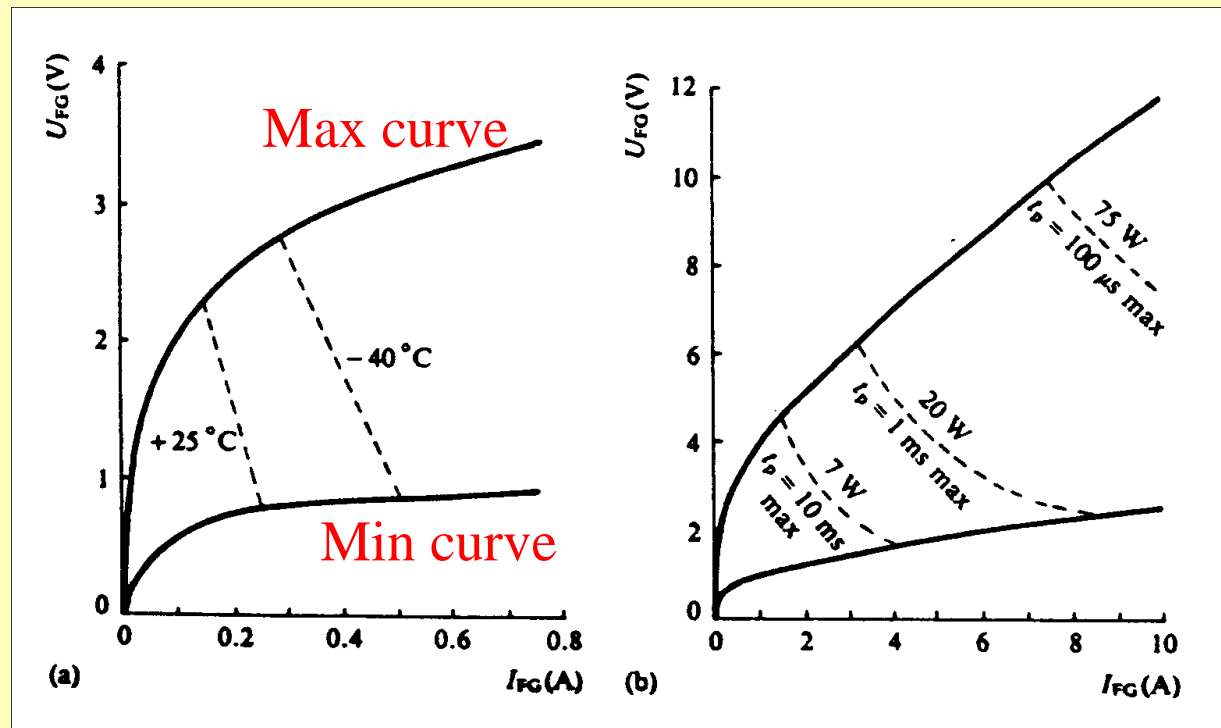
4. Drive circuits



Demands

- Safety turn-on
- Normally galvanic isolation
- React with minimum delay
- Noise immunity (small capacitance)
- Simple and cheap
- Small losses
- Limit the amount of supplies

Thyristor input characteristic 4. Drive circuits



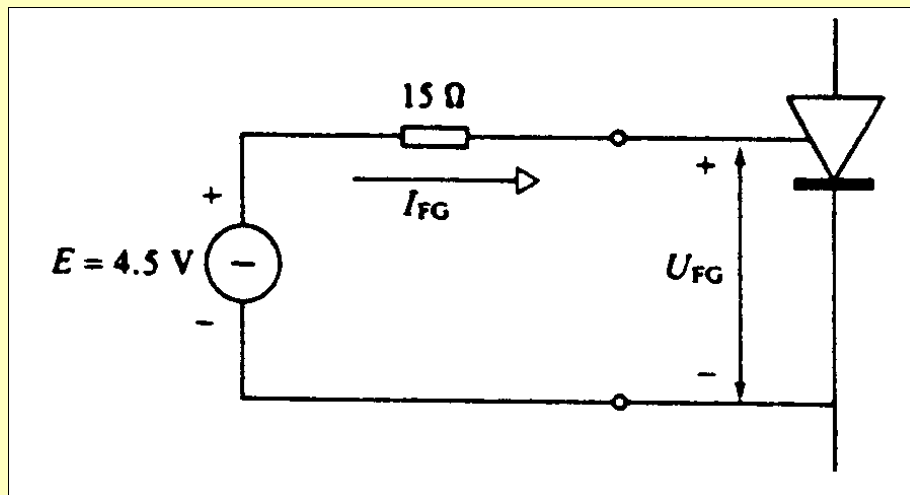
Problems

- Minimum trigger current
- Temperature dependence
- Variations in different components

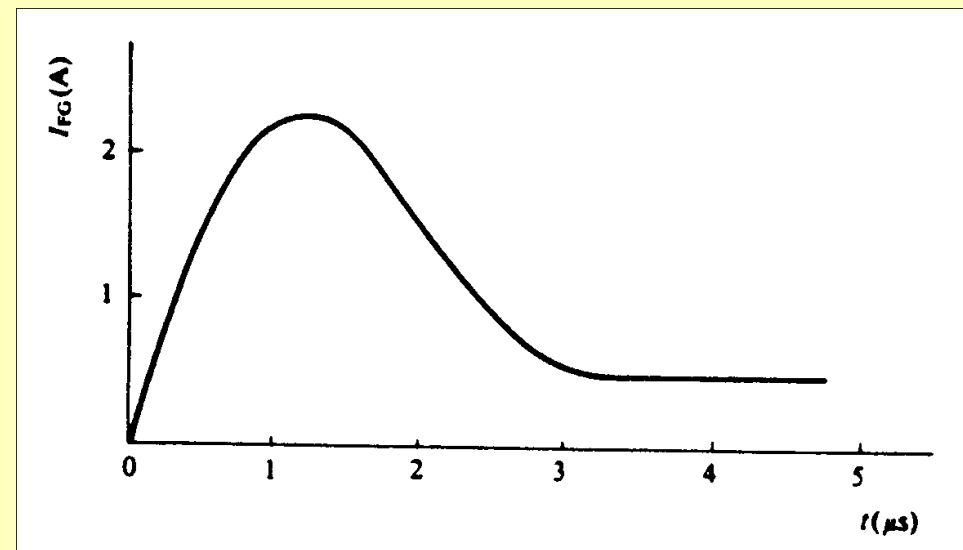
A kind of diode input characteristic

4. Drive circuits

Idealized drive circuit



Idealized current pulse



- Large initial current pulse \Rightarrow Safety turn-on
- Small initial current pulse \Rightarrow local turn-on \Rightarrow destruction

Galvanic isolation

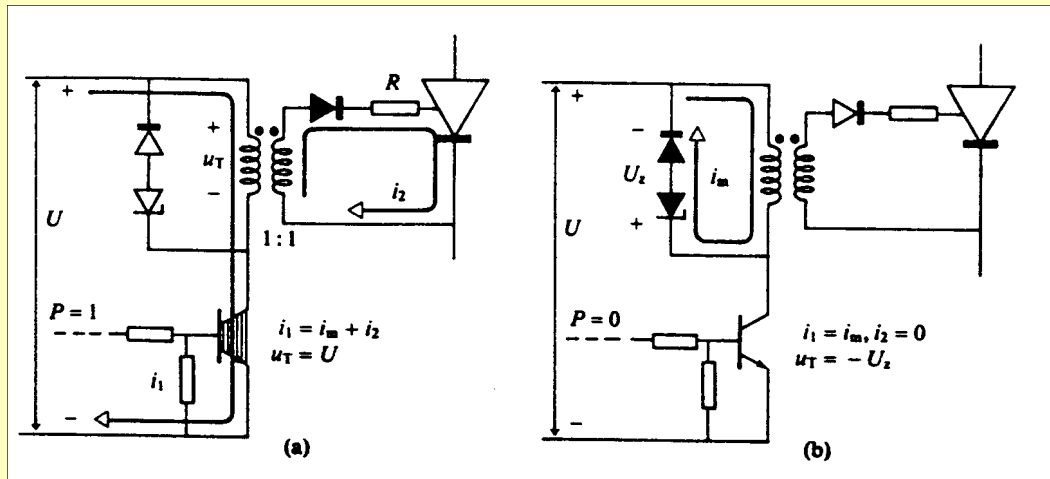
4. Drive circuits

1. Pulse-transformer ⇒ Turn-on energy is also supplied
2. Optocoupler ⇒ Energy for turn-on is not supplied.
Extra supplies is required. Fast
3. Light ⇒ Energy for turn-on is not supplied.
Extra supplies is required. Fast and very
noise immune.

Today is light-conductor and Thyristor integrated.

4. Drive circuits

Simple drive-circuit with transformer



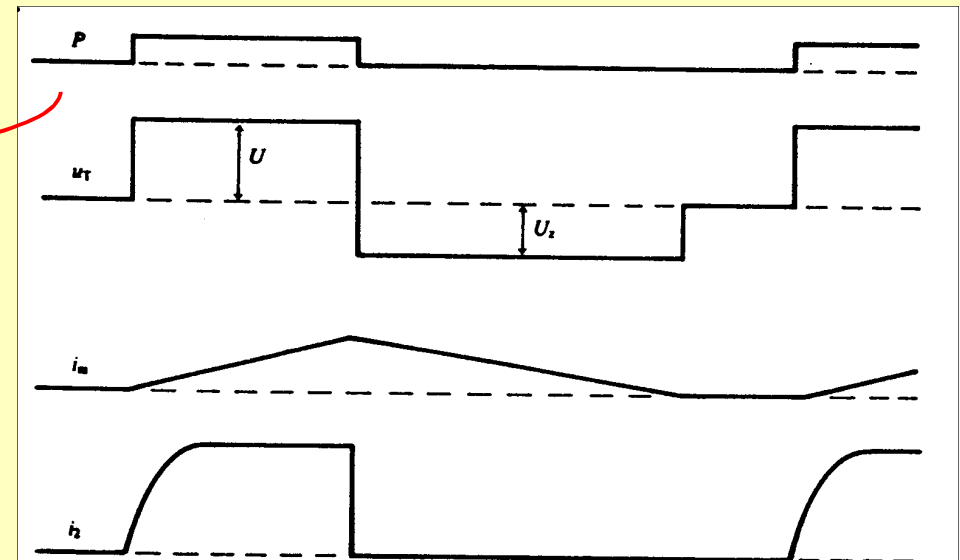
Waveforms

1 pulse

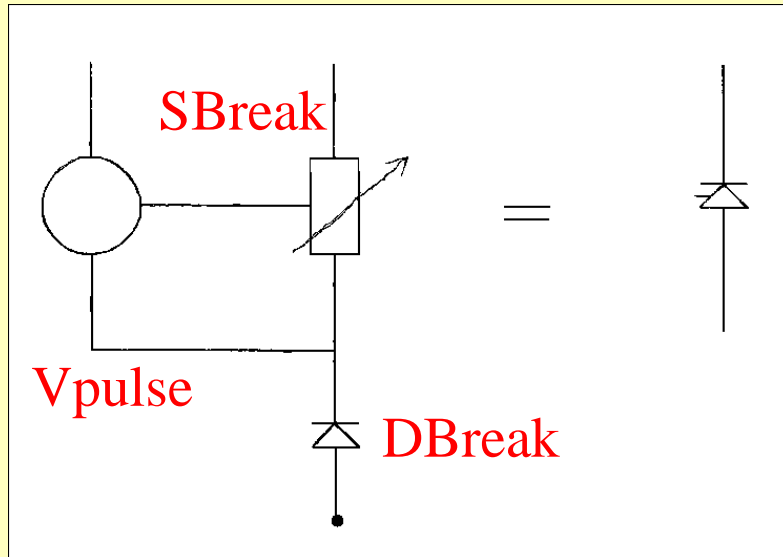
- Large main field inductance.
- Large amount of fringing.

Many pulses

- low main field inductance.
- Low amount of fringing.

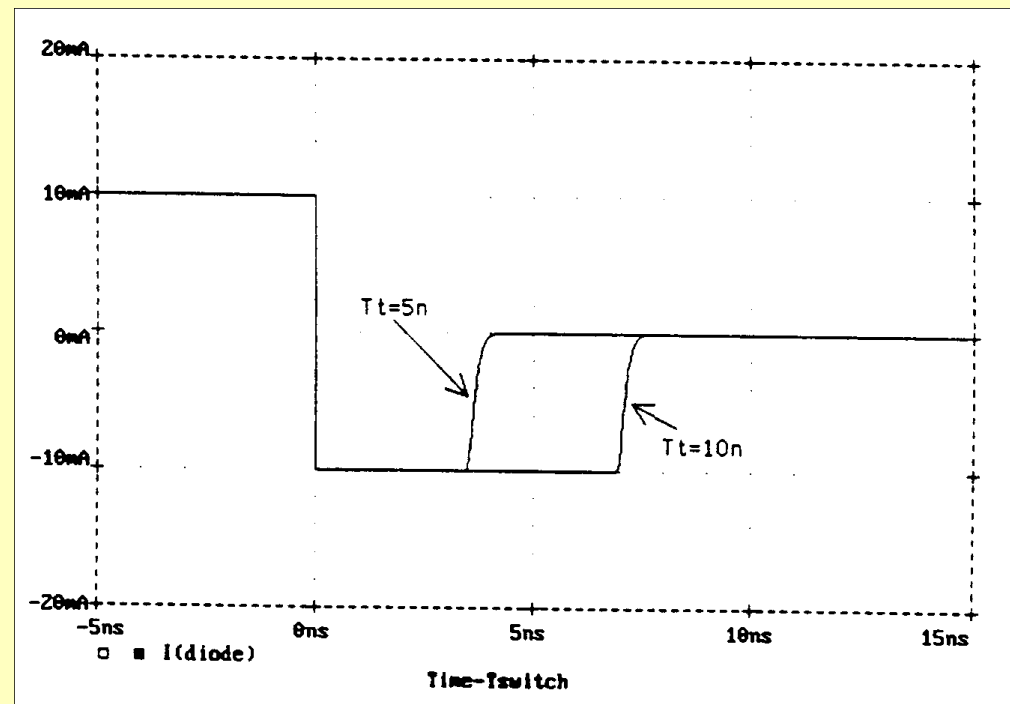


Simple Thyristor model 5. Modeling reverse recovery



The Diode has a reverse recovery model

Simulation result :



Important

Transit time T_T : Time for the carriers to leave the diffusion layer

Capacitance C_{j0} : Capacitance in the diode under blocking state.

5. Modeling reverse recovery

Charges before turn-off

$$Q_F = \tau I_F$$

τ the charges life-time

Charges after turn-off

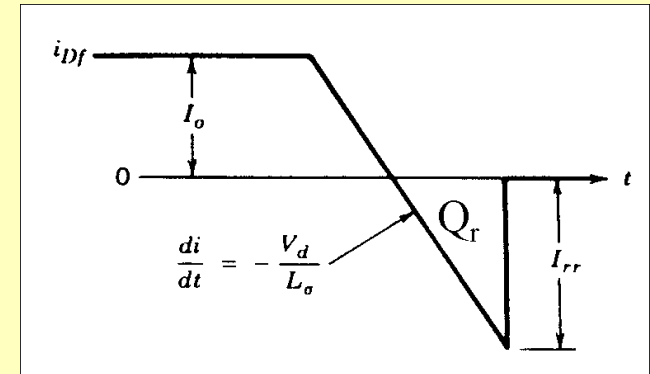
$$Q_R = \frac{1}{2} t_{rr}^2 \left. \frac{di}{dt} \right|_{off}$$

No recombination

$$t_{rr} = \sqrt{\frac{2\tau I_F}{\frac{di}{dt}}}$$

Or

$$I_{RR} = \sqrt{2\tau I_F \frac{di}{dt}}$$



τ can be estimated from data-sheets and be used as TT in the diode model.

Limits

- No “SOFT” turn-off. But OK because snubbers often is designed in worse case.
- Capacitor is not OK for a high-voltage diode.

7. Exercises

Look at Course home-page